

OSA-CBM stands for Open System Architecture for Condition Based Maintenance.

This specification is offered by the MIMOSA organization. Information on this organization can be found at [www.MIMOSA.org](http://www.MIMOSA.org)

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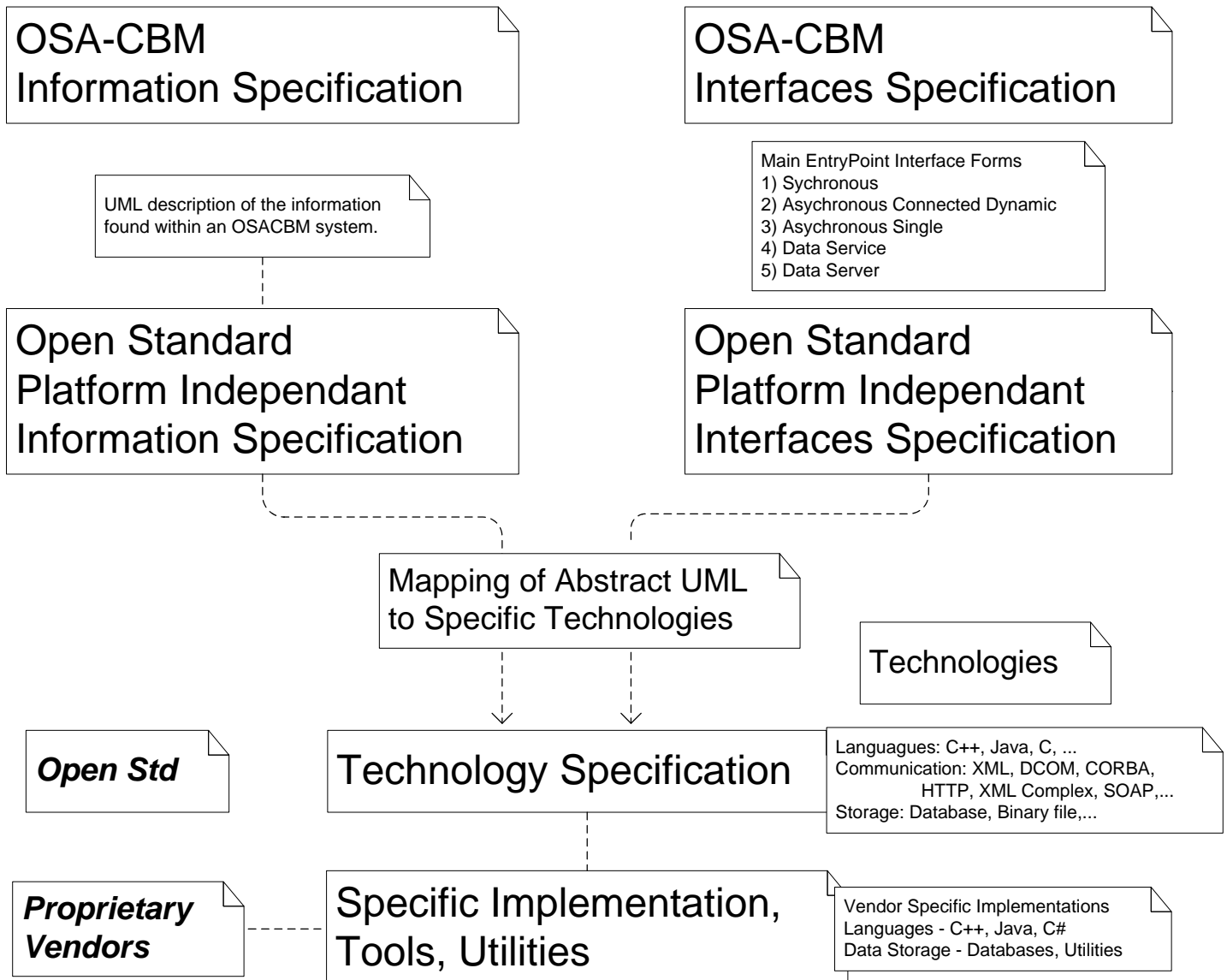
The version of OSA-CBM 3.1 corresponds to the OSA-EAI version 3.1

This is the version referenced in ISO 13374 which is a CBM standard.

This OSA-CBM is based on the work supported by the Office of Naval Research under Agreement No N00014-99-3-0011 OSA-CBM Boeing DUST.

This version has been modified from the original OSA CBM 1.0 DUST program specification within the MIMOSA organizational process.

These modifications improved the specification in capability and compatibility to the MIMOSA OSA EAI specification and its advancements.



This specification is designed for multi-technological implementation. From this point the UML need specific mappings into network protocols, MIMOSA OSA EAI CRIS for database, and languages. This document covers the abstract UML description of the specification.

This architecture splits the information specification which defines the information that can be moved around in a CBM system, from the interfaces that can be used to move that information. This separates the information that is moved, stored, and processed from the mechanism that accomplishes that task

An implementation of this technology will select applicable interface(s) and merge the information specification into a complete package.

The information specification and interface specifications as they are created will be found in other documentation.

Specific technological implementations may be vendor IP supplied tools and utilities. Such vendors are encouraged to be MIMOSA members.

## Technology Specification

This document covers the OSA CBM abstract UML specification. It defines the core specification of the information found in a CBM system. The Interface specification offers ways to move that information around.

From this specification a mapping effort is required to convert this into a specific technology representation that is verifiable. For example, a mapping of the UML Information specification to XML will result in an XML schema that specifically defines the XML form of the data. The XML schema will then be used to validate a system that is required to output OSA CBM XML.

## Notes on Compliance

### Information Specification verses Interface Specification

The information specification describes the type of information found in a CBM system. OSA CBM was developed in close connection with the MIMOSA OSA-EAI CRIS 3.0.

The interface specification(s) describe methods of moving the information around. One difficulty with developing this was that different technologies have different ways of achieving this goal. There are already existing standard ways of moving XML

The initial goal for OSA CBM 3.1 technology mapping will be an XML schema for the information content form only and leave it up to application developers to select the existing technology of choice for them to move the XML around.

Compliance will be based on XML conforming to the standard schema.

## Interfaces

### Interface Types

- 1) Synchronous
- 2) Asynchronous
- 3) Data Service
- 4) DataEvent Server

Why so many interface types? OSACBM is a specification that covers a broad technological base. The main aspect of value for OSACBM is its information specification. That information specification was designed with concepts in mind as how to map it to programming languages, transfer protocols, and data storage devices.

There are several interface types that are required for wide standard applicability. Each technological implementation will likely not implement every interface. Rather the technology of choice will typically select the interface(s) by logical choice.

Example: A Web server returning XML over HTTP is a Synchronous - Stateless

### Definitions

#### Interface

An Interface describes how information will be moved.  
A request is made to get information from an object.  
A notify is made to input information into an object

EntryPoint - the interface presented by an object to the outside world.  
It provides direct access to the top level classes.  
For example, the DataEventSet and Configuration classes.

EntryPointSink - Asynchronous data return path for requested information.

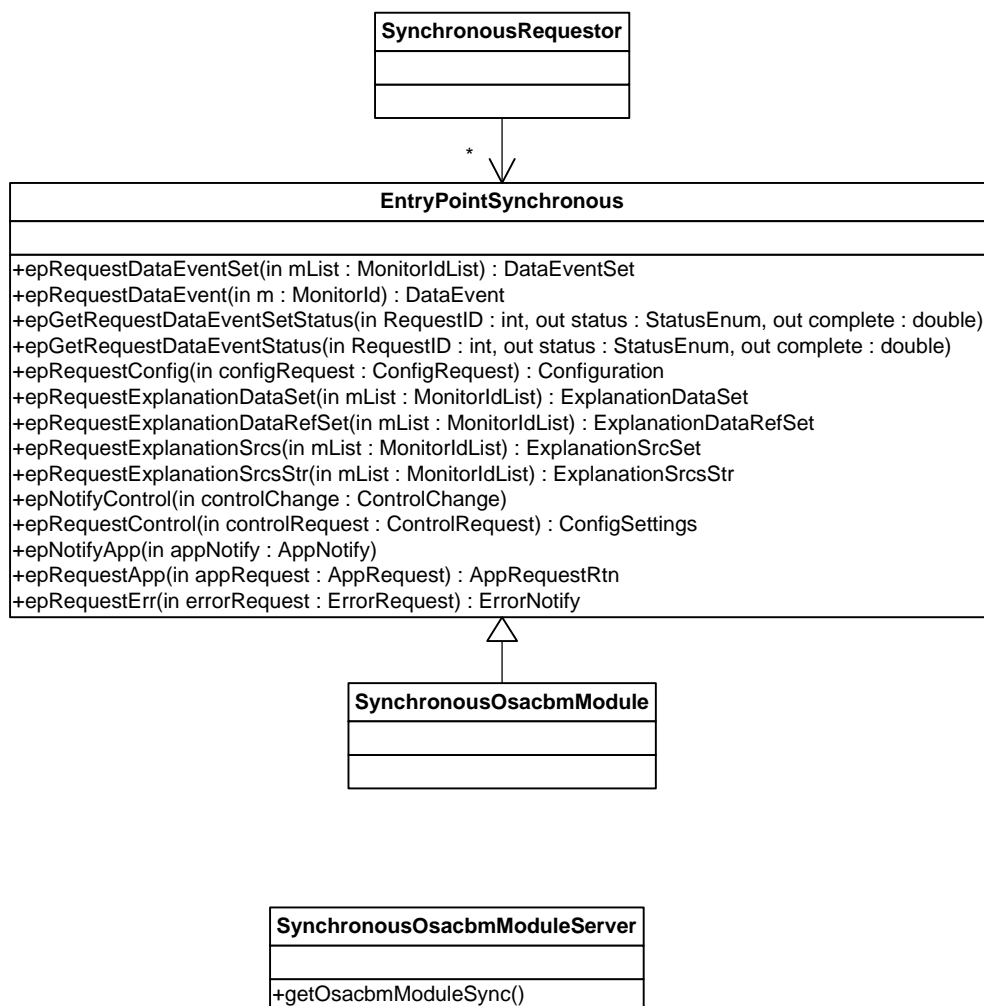
Synchronous Interface - Information is returned by the Request method.  
Asynchronous Interface - Information is returned as available via EntryPointSink.

## Interface Synchronous - Stateless

**Note: Details of this interface are under review for revision to a sequence based capability.**

The synchronous interface returns data with the call.  
It models the Web XML over HTTP fetch methodology

Example:  
newData = moduleEPptr->requestDataEventSet( );



The SynchronousOsacbmModuleServer interface is suggested method to create many Synchronous servers for one specific Osacbm Module.

There are cases where a data user module may be setup for

## Asynchronous Connected Module Interface

The asynchronous interface

1) allows for any number of higher modules

2) two-way connection is established and maintained for duration of need.

The sinkId and epId are used for specific sink and entry point identification.

The two-way connection has several feature advantages

2.1) it is typically faster in usage since the overhead of connection occurs only once.

2.2) It allows for three different modes of communication are possible

2.2.1) Return on Request) main OSACBM 1.0 style of communication

2.2.2) Return when threshold is exceeded.) The connection can be setup for notification only one threshold crossing.

2.2.3) push all) The lower module pushes data to the higher connected module for every frame without the need for request before hand.

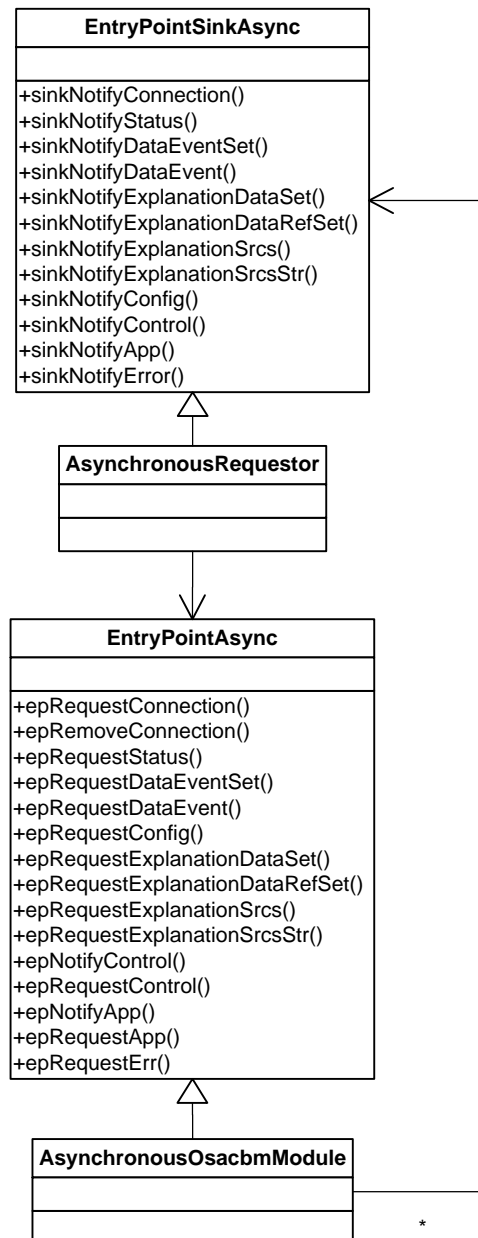
3) Example method call interplay with the connection oriented Asynchronous Interface.

// A higher module requests data from lower module that it previously established a connection with

lpEp\_lowerModuleWithData->requestDataEventSet( lpRequestingModuleEPSinkptr );

// The lower module returns data when it is ready

lpSink\_higherModule->notifyDataEventSet( data );



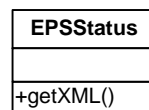
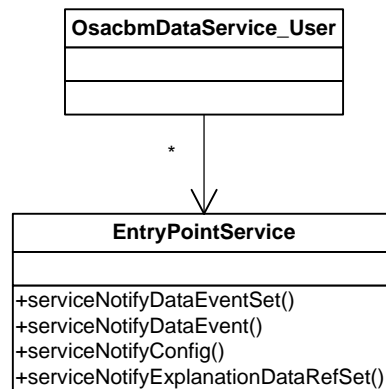
EntryPointService is a one way data input device.

An EntryPointService is a well known location service of a well known function.

Two possible uses would be

- 1) data storage utility
- 2) maintenance advisory receiver service

The first four methods for DataSet, DataEvent, Config, and Explanation are the main ones expected to be used.

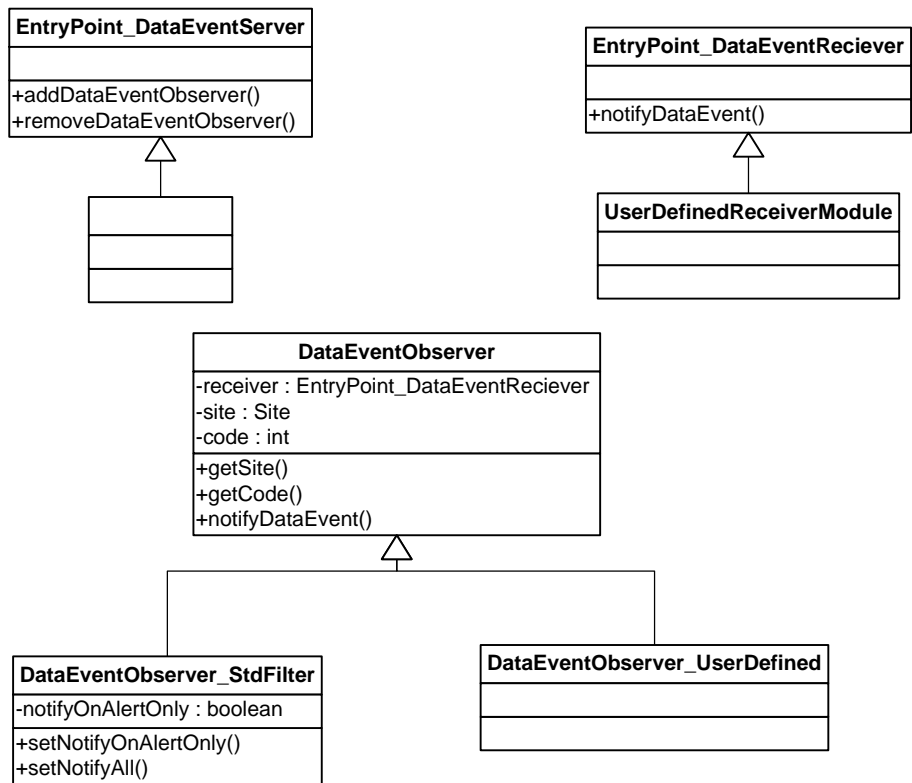


EPSSStatus is a return indicator of how an input message was received.

**DataEventObserver**

In many systems, signals are moved individually.  
This page describes an interface mechanism for handling individual DataEvent in a very simplified interface.

The UserDefined\_DataEventObserver can be programmed by the user for special handling of the signal.



## Information Specification

The Information specification describes in UML the information found in a CBM system. This UML was developed in conjunction with OSA EAI 3.0 level CRIS.

There are six main categories of information

Dynamic Data	(on platform)
Configuration Data	(not typical for on platform)
Explanation Data	(on platform optional)
Control Data	(simple user option)
App Data	(simple user option)
Error Data	(simple user option)

Each of these is individually addressable in the interface. That is a request is made for a DataEventSet and a DataEventSet is what it gets. A request is made for Configuration and Configuration is what it gets.

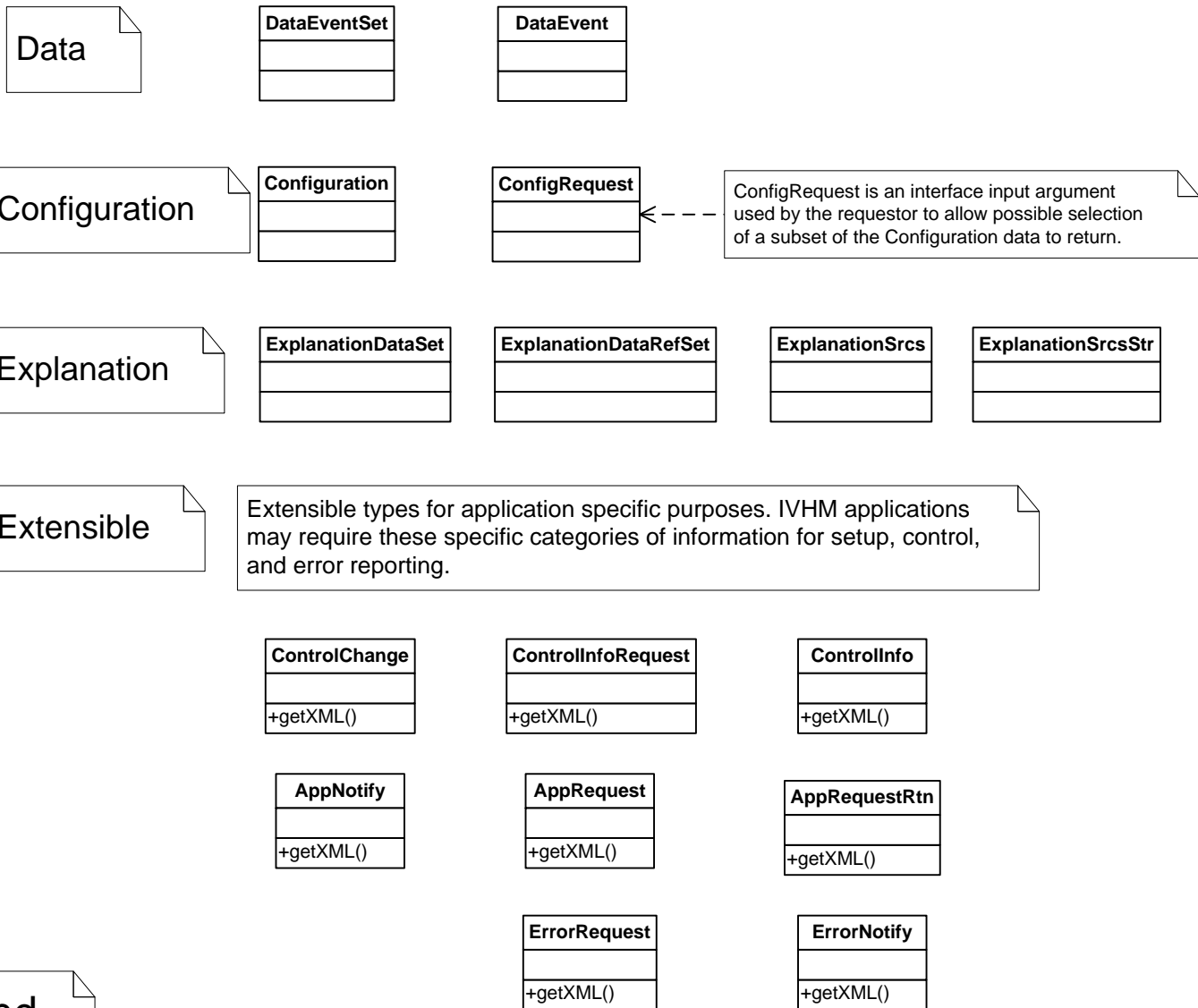
It is suggested that only Dynamic Data is required to be used in embedded systems such as a small platform IVHM system where configuration is static and engineering units are built in. The addition of configuration data especially forces users to put into these systems information not typically found there. That adds development time for something of very limited or no use with in its present realm.

For such systems, a MIMOSA server may exists at servicing locations which contains the configuration information.



## Information Specification - EntryPoint Classes

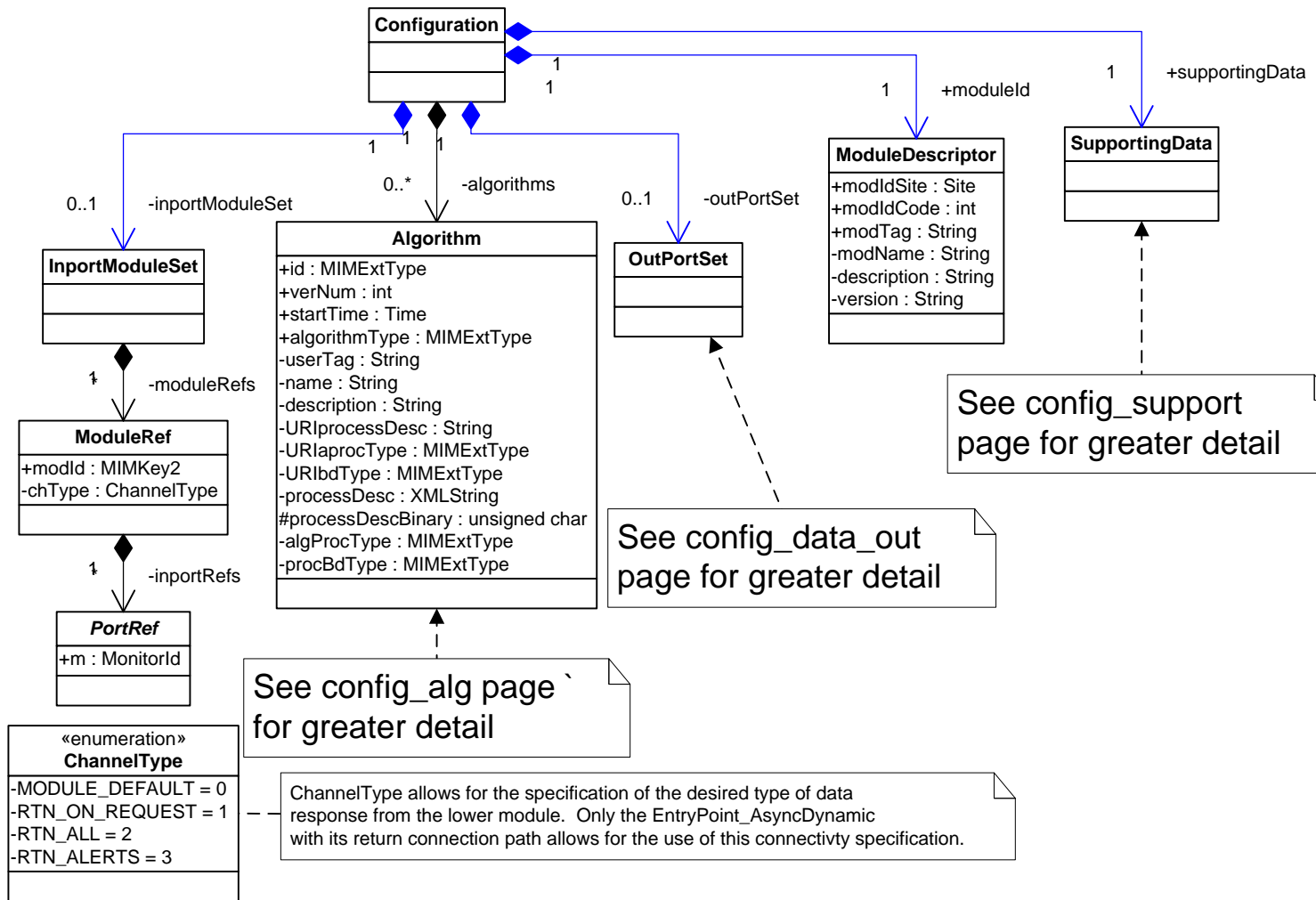
The EntryPoint interface provides direct access to the following classes. The remaining thrust of this document describes their details in UML form.



The Legend explains some of the OSA-CBM specific nomenclature. Note especially the '-', '+', and '#' used to indicate paramter optionality and count.

# Configuration

Configuration gives information about an OSA CBM Module's input sources, description of algorithms used for processing input data, a list of outputs various output specifics such as engineering units, thresholds for alerts, etc.

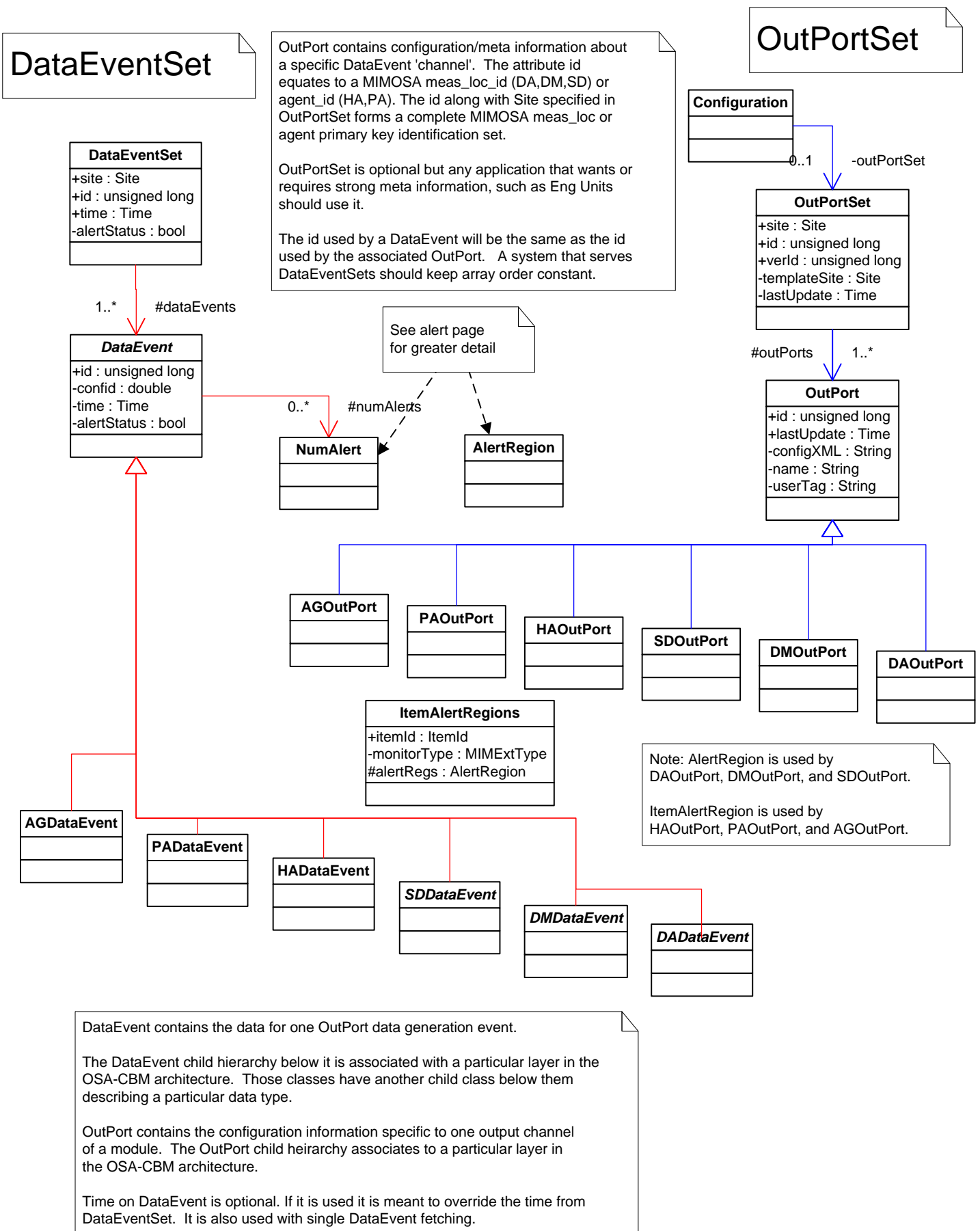


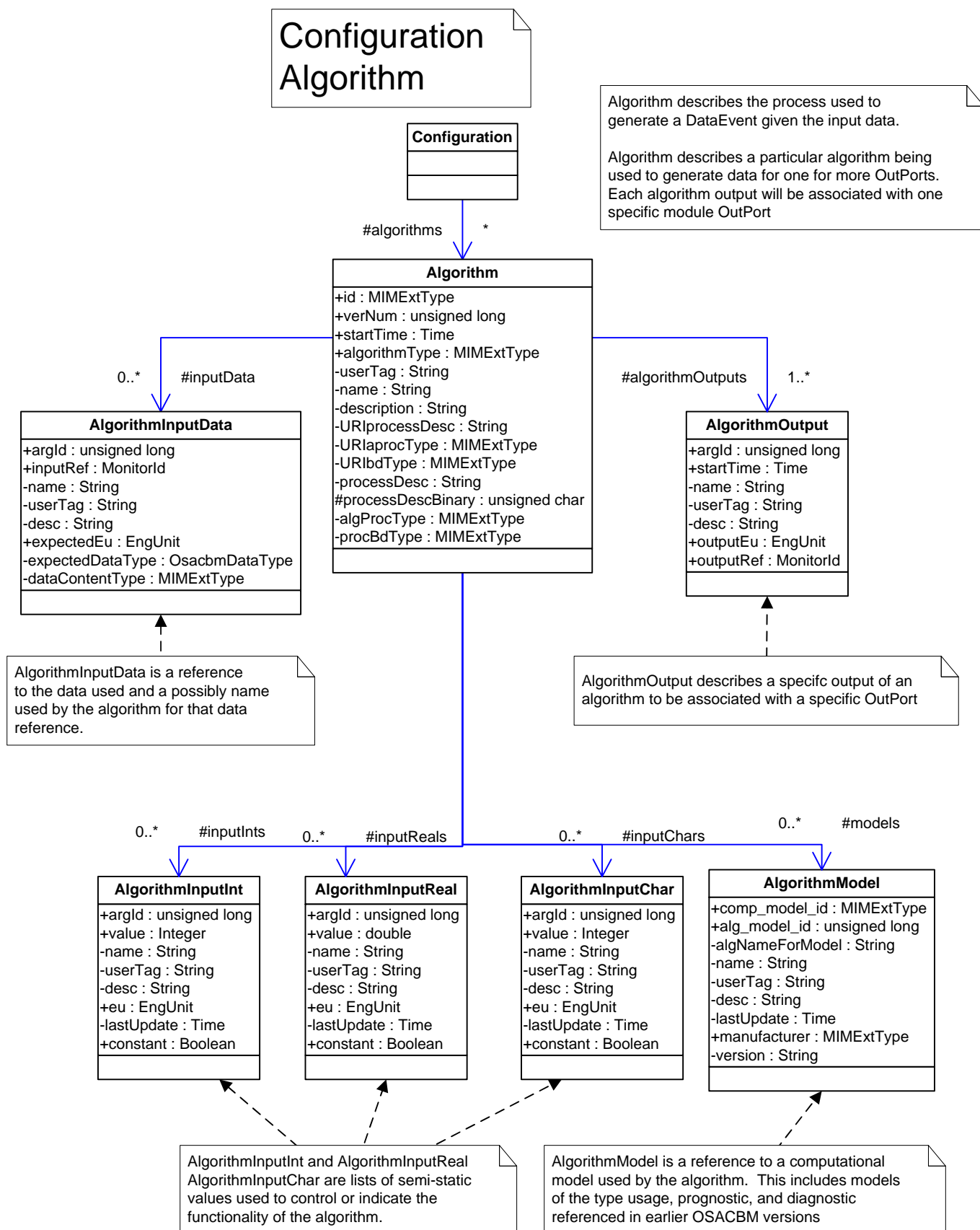
InportModuleSet gives information about where a module gets data from.

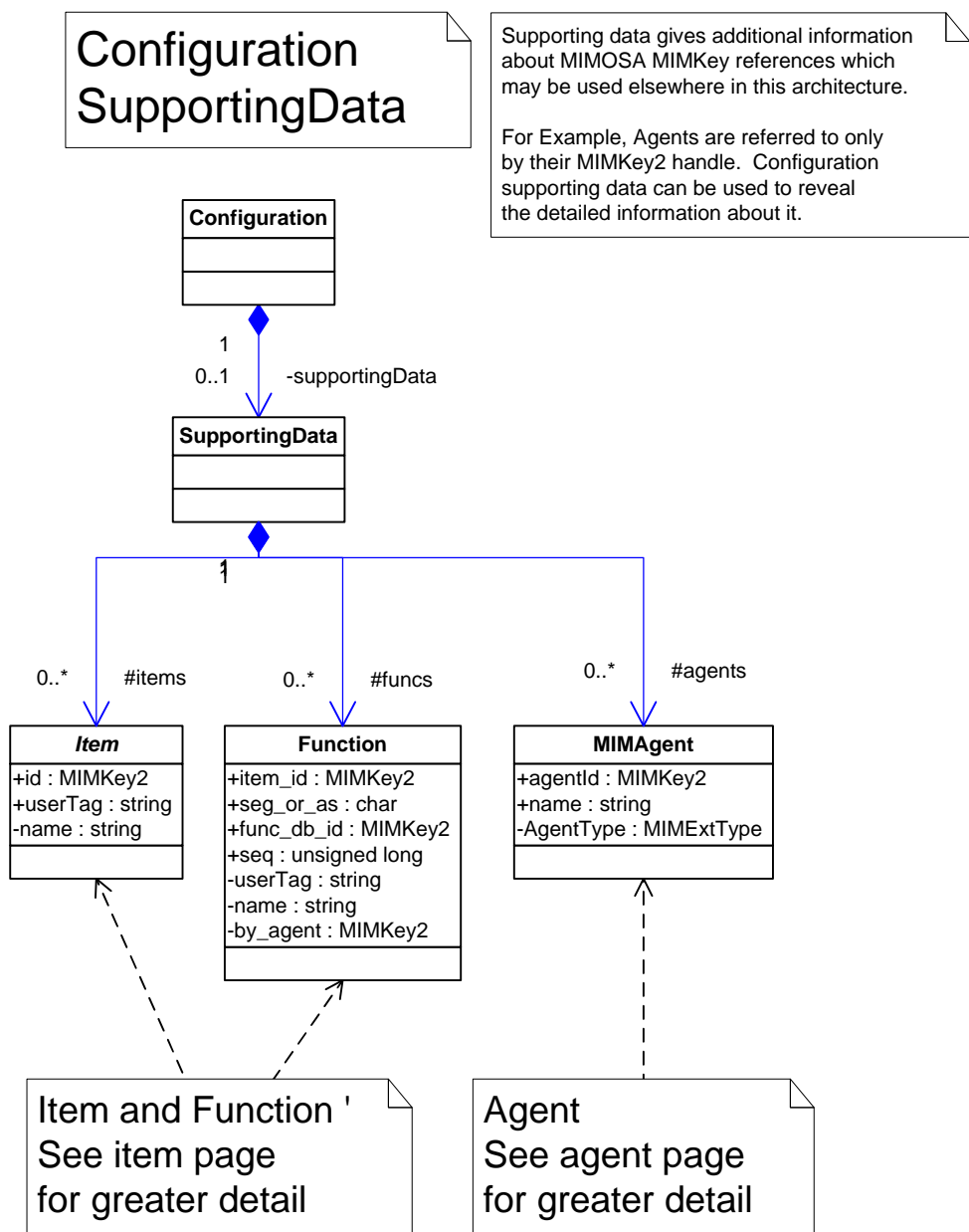
Algorithm describes the process used to generate a DataEvent.

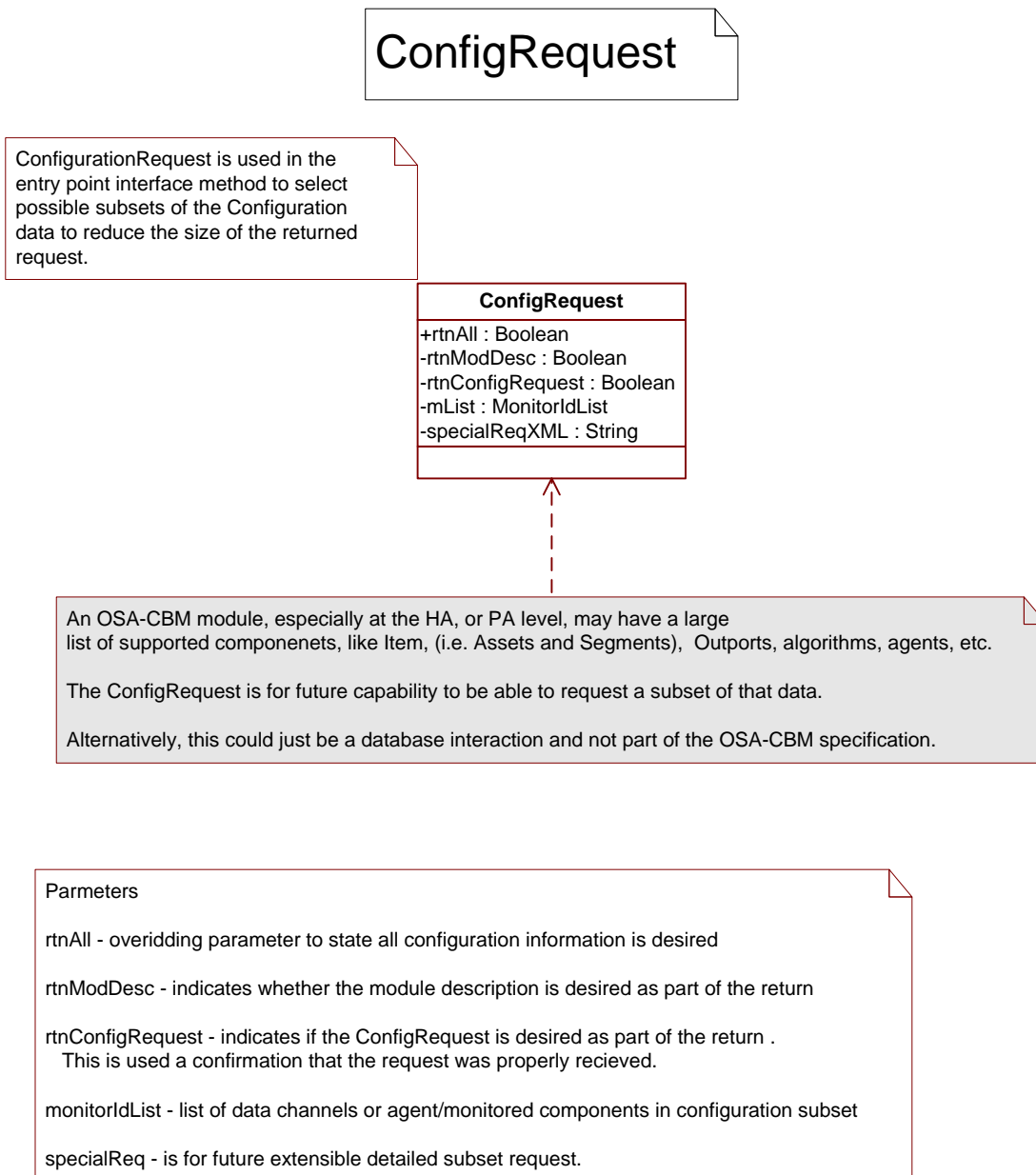
OutPortSet lists each of the OutPort. An OutPort is a 'data channel' and the OutPort class gives specific configuration data for that data channel.

Supporting data gives additional information about MIMOSA MIMKey or primary key references which may be used elsewhere in this architecture.









## Explanation

Explanation is the Data or a Reference to the Data used by a module to produce an output.  
The OutPort algorithm is a description of that process.

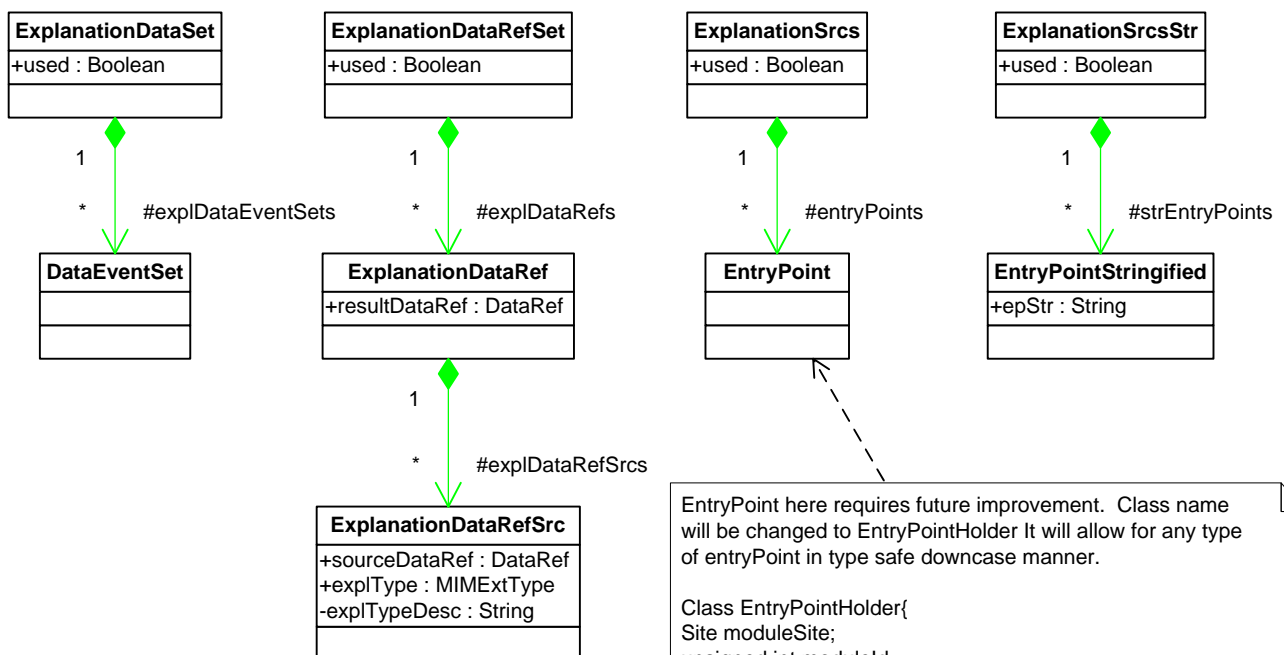
Explanation consists of four possible necessary forms depending upon the application.

The first is simply the data used for a calculation.

The second is more of a handle / timestamp type of reference to the data used. This is used when the data comes from a well known location or is known to be stored. The main example is using data stored in a database.

The final two forms are two different ways of giving direct access to the modules supplying the data. One is a set of direct pointers to modules. The other form is a "stringified" form of pointer that will allow a user to construct a pointer to the module.

## Explanation Forms



There will be many types of standard MIMOSA OSA CBM explanation types.

### Note on "used" boolean

Note, if a form is not used, then just set the boolean 'used' to false and return an empty set.

EntryPoint here requires future improvement. Class name will be changed to EntryPointHolder It will allow for any type of entryPoint in type safe downcase manner.

```

Class EntryPointHolder{
  Site moduleSite;
  unsigned int moduleId;
  EntryPointType epType; // MIMNonExt
};
  
```

```

Class EntryPointHolder_Type1:public EntryPointHolder{
  EntryPointHolder_Type1& ep;
};
  
```

## Extensible Components

These are called the extensible components because they are very application specific. In order to handle a variable content message the interface is defined to be an XML string for inter-process communication.

A specific use may be designed with UML and have a XML mapping. A specific language implementation may use the UML class form. Any serial communication needs, like HTTP, DCOM, or CORBA over ethernet, may then convert the UML into the XML form and use the standard interface without the need to develop another communication interface.

Note once again, these are application specific!  
It is fine if a small embedded system does not want to use them or wants to use them in a very narrowly defined way.

### Control Specific

Control is the concept of being able to change module parameters on the fly.

One major use would be to be able to change a thresholding alert monitor's threshold settings on the fly to adjust to present operating conditions.

### Application Specific

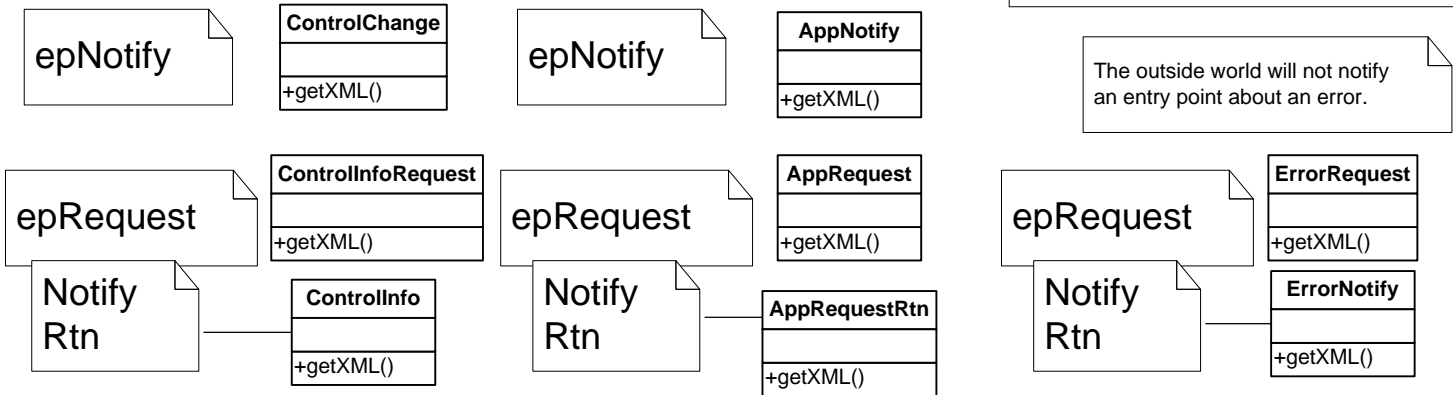
App specific is the concept of being able to interact with a module in an application specific way.

One possible use might be to request extra non standard information about a module.

### Error Specific

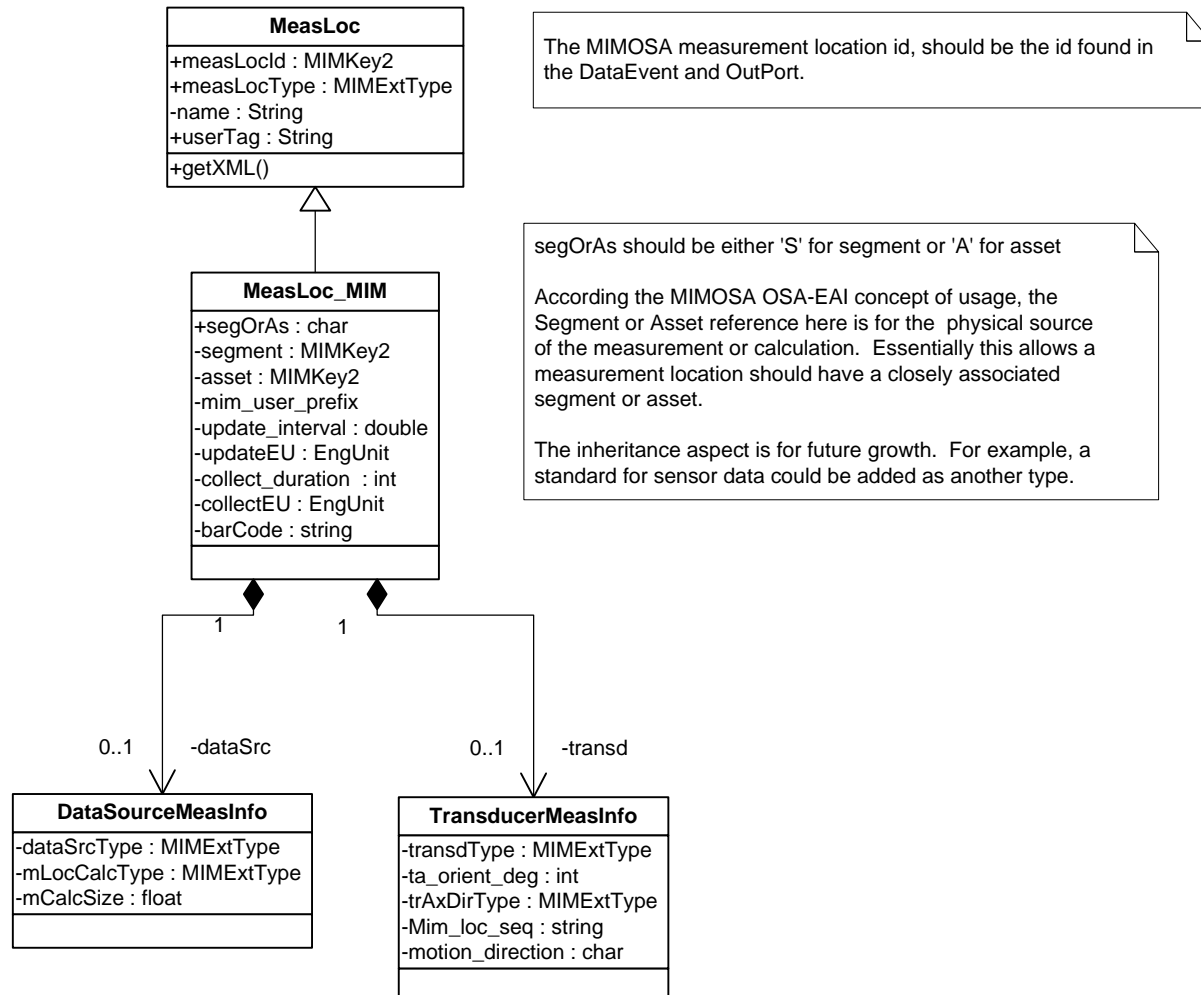
Error specific is the concept of indicating an error condition. Errors are application specific. However as the standard progresses specific activities may start to standardize errors. For example, invalid web requests using XML over HTTP will have standard return response.

Note, Connected state configuration will allow for unsolicited error notification.

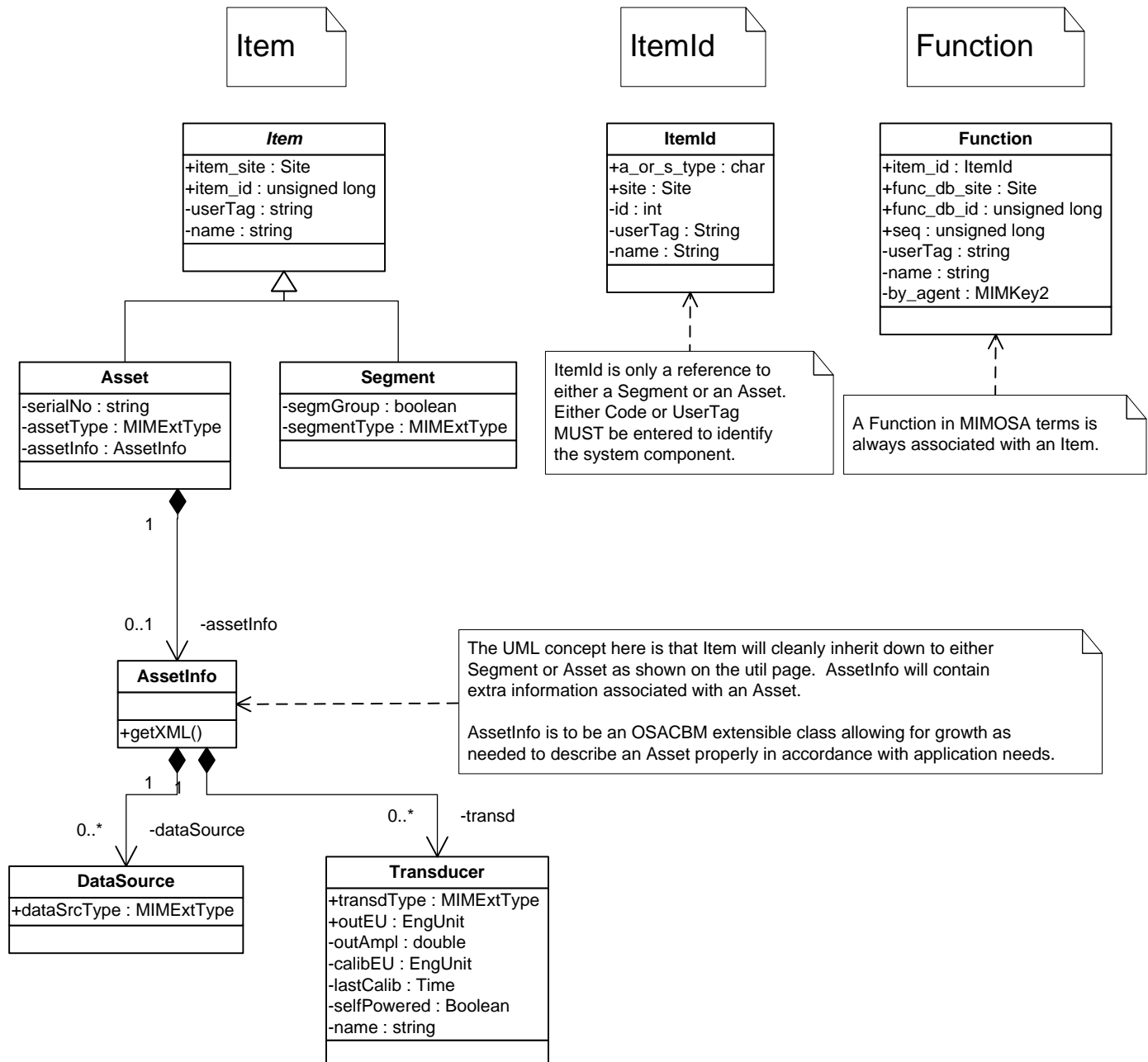




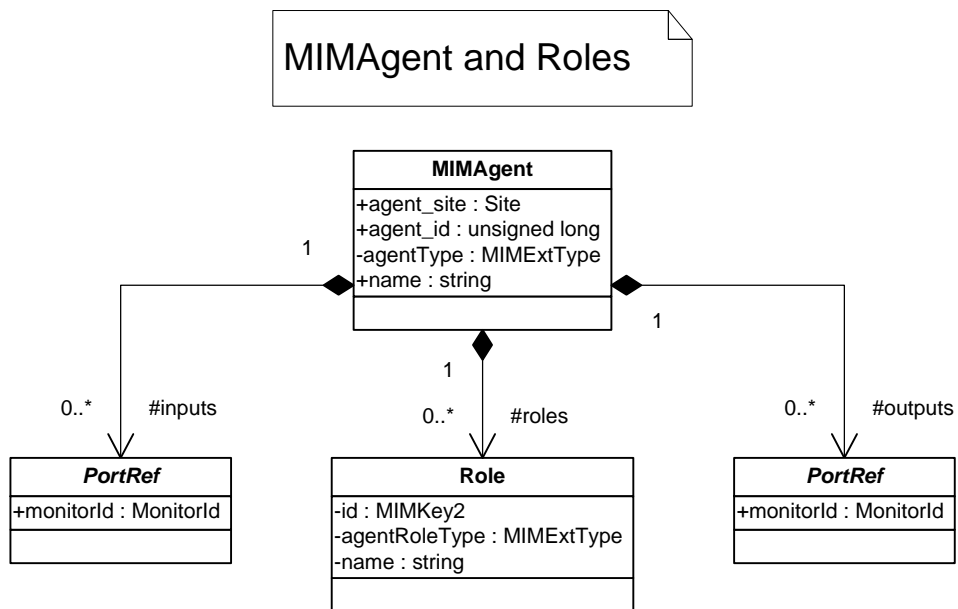
## Measurement Location (DA, DM, SD)



The Item page details out the Item and Function classes that may be used or referenced elsewhere in this document.



The Item page details out the Agent class that is referenced elsewhere in this document.

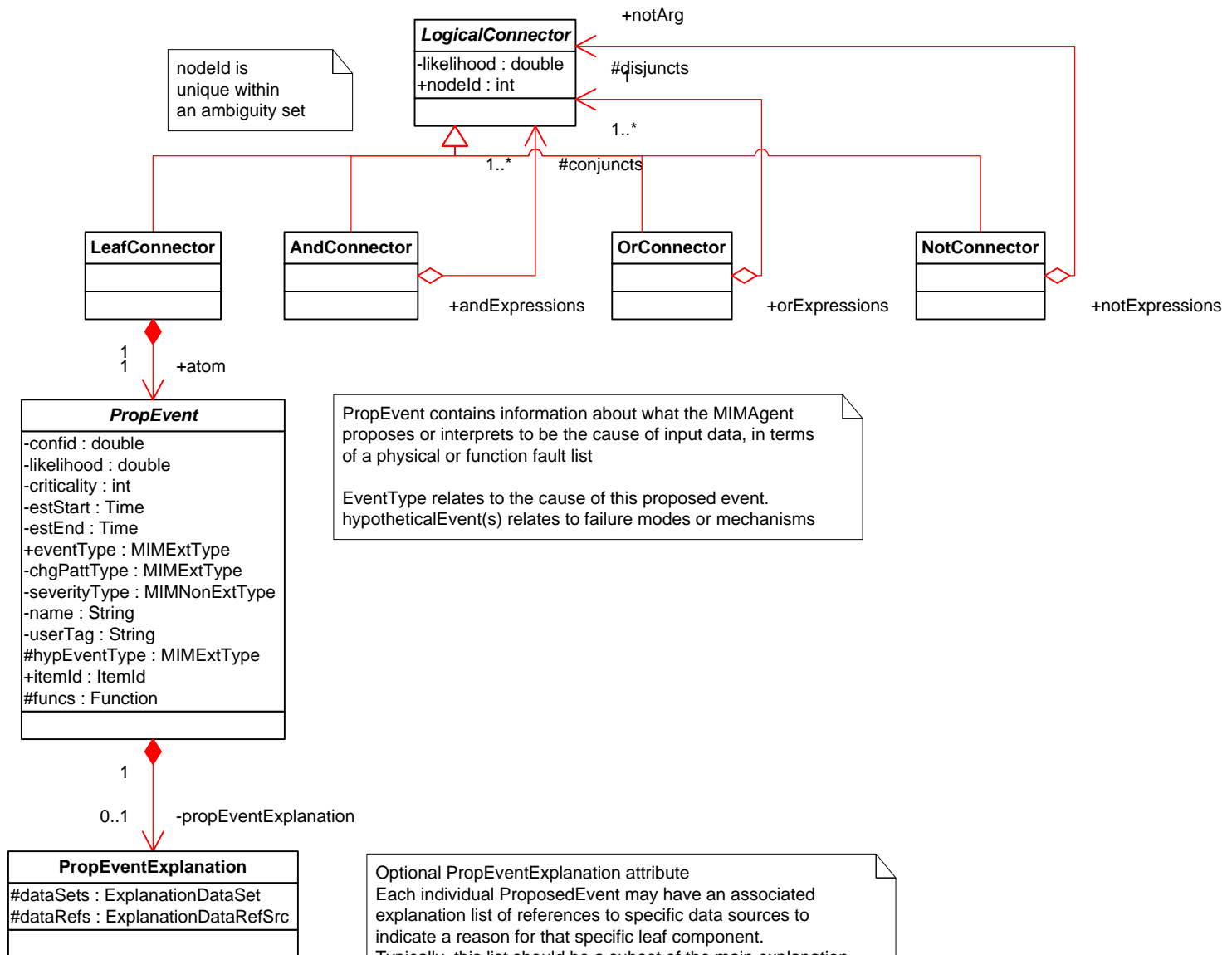


## Proposed Event for Failure Descriptions (HA,PA)

The LogicalConnector provides for any style of ambiguity group by using combinations of the AndConnector, OrConnector, and NotConnector classes.

The LeafConnector class gives information about the proposed event fault.

A single LeafConnector without using the And, Or, and Not Connectors is the simplest form used to describe a single determined fault.



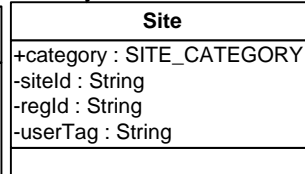
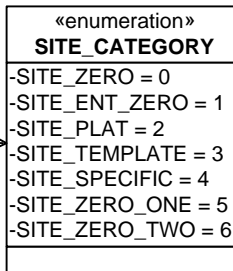
## Site

Site is globally uniquely identified by one of two methods. Either the MIMOSA assigned 16 hex character siteld or the (regld, userTag) string combination where regld is assigned by MIMOSA for a specific registered user and the userTag is uniquely assigned by the registered user for each of the registered user's mobile platforms.

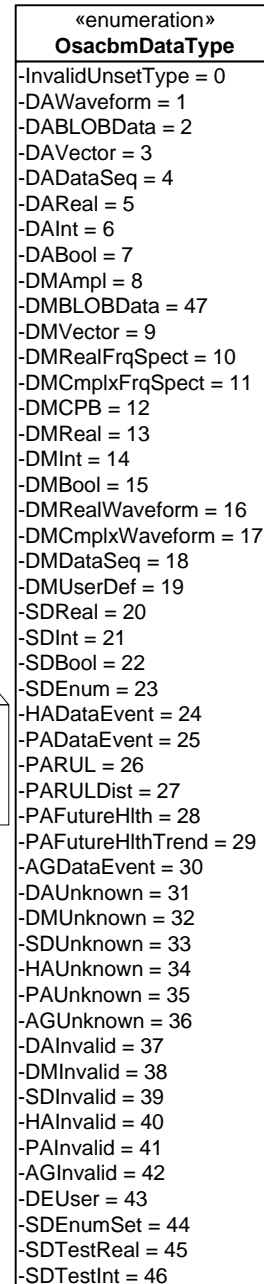
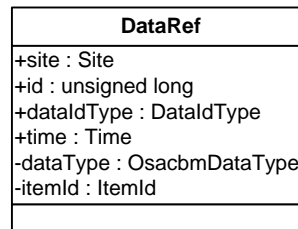
More specifics on these strings is described in the MIMOSA Chris documentation.

SITE\_CATEGORY indicates specific site types

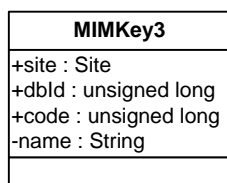
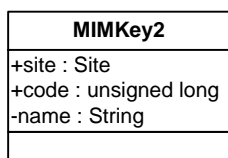
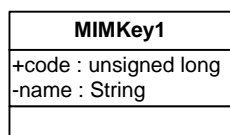
SITE\_PLAT is for site platform  
 SITE\_ENT\_ZERO is for platform enterprise site zero entry  
 SITE\_TEMPLATE is for platform template  
 SITE\_ZERO is MIMOSA (0, db\_id=0)  
 SITE\_ZERO\_ONE is MIMOSA (0,db\_id=1)  
 SITE\_ZERO\_TWO is MIMOSA (0,db\_id=2)  
 These are standard MIMOSA entry sets.  
 SITE\_SPECIFIC for all other sites and needs to be added into the system directly or indirectly



## DataReference



## MIMKeys: MIMOSA Table Keys

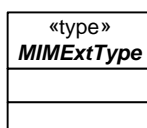
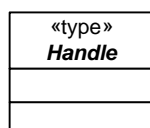
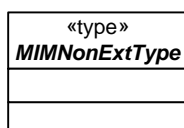


MIMKey Type Defs

```

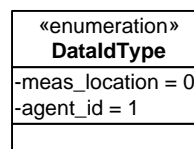
typedef MIMKey1 MIMNonExtType
typedef MIMKey2 Handle
typedef MIMKey3 MIMExtType
  
```

DataRef is a reference to one data item. It in essence is a descriptor to one DataEvent value. Explanation uses this to be a type of data pointer. Item is used to describe an agents assessment for an item at a particular time

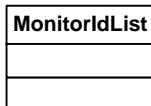


MIMNonExtType is a MIMOSA non extensible type. It is therefore a single integer.  
 Handle is used to indicate a specific MIMOSA measurement location (DA, DM,SD) or agent id (HA,PA,AG)  
 MIMExtType is a MIMOSA extensible type. It has three keys, the site, dbld, and code. (Handle, code) may be put into a MIMExtType number to form its value. In this case it would typically refer to a MIMOSA database id

## DataIdType

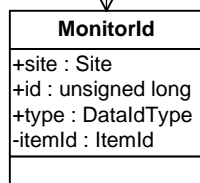


## MonitorIdList



0..1

-monitorId



MonitorIdList is used by interfaces to indicate the desired subset of served information by indicating the monitored measurement location, agent, or agent / item that is desired.

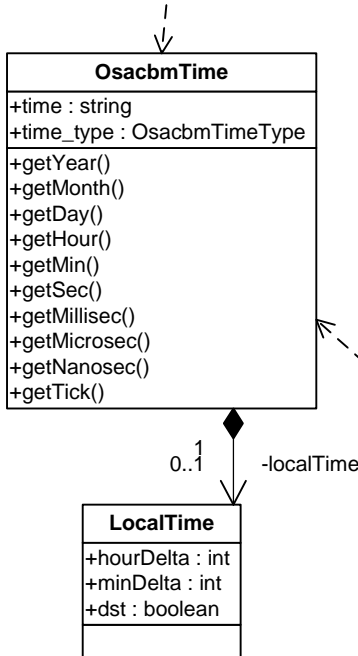
MonitorId is a reference to a monitored measurement location, agent, or agent / item

DataIdType describes what a DataEvent id is meant to be a reference to. OSA CBM DataEvents from the lower three layers DA, DM, and SD are MIMOSA measurement locations. OSA CBM DataEvents from the higher three layers, HA, PA, and AG are MIMOSA agents. The DataEvent ID's from these different data types therefore correspond to these two types of sources: agents and measurement locations.

## Time

The utility page details out some classes that may be used or referenced elsewhere in this document.

The osacbm uses the name OsacbmTime to eliminate name clashing with other technologies



Time has been expanded to have a few different internal content form types. This is to allow the simplest most direct method of handling time to be incorporated in an embedded program.

MIMOSA type should be transmitted as a string conforming to the ISO 8601. See description at side

Tick time presently defined if for microseconds. This is in terms of a long long. It is in terms of ticks since start up of program

Posix is Unix type time also fetched in terms of the long long.

The getMicrosec(),...getMin() methods should interpret Tick or Posix accordingly

Methods to access specific time portions is highly desirable for any implementation.

All rtn types are integer EXCEPT getTick which is unsigned long long 64 bit int

Date/time in ISO 8601 variable length character form:  
YYYY-MM-DDThh:mm:ss.ffffff  
example 2006-05-31T14:30:33.123

where:

YYYY = four-digit year  
MM = two-digit month (01=January, etc.)  
DD = two-digit day of month (01 through 31)  
hh = two digits of hour (00 through 23)  
(am/pm NOT allowed)  
T = literal "T" character  
mm = two digits of minute (00 through 59)  
ss = two digits of second (00 through 59)  
ffffff = represents a decimal fraction of a second to the billionth of a second

Year, month, and day must be specified. Additional timestamp content should be provided, if known. Zeros will be assumed for the omitted values. Negative DATETIME is not supported. All suffixes after the 29th character provided in the ISO 8601 specification, such as "Z" (representing Coordinated Universal Time (UTC)), are not necessary since the CRIS specification explicitly manages local offset hours and minutes as distinct columns associated with the UTC (referred to in the CRIS specification prefixed with "GMT") column.

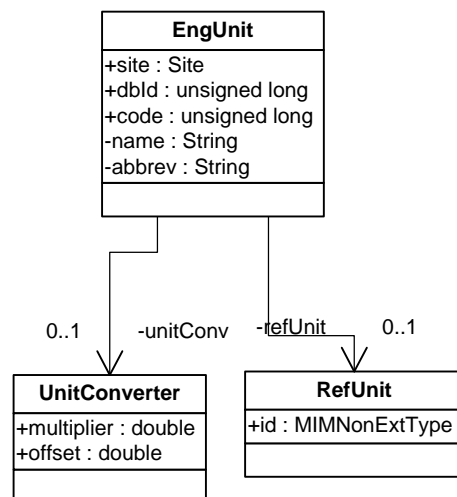
Note that the actual difference between the new DATETIME(10:29) data type and the CRIS V2.1 fixed-length STRING(29) form is the separator between date and time information is now a literal "T" instead of a blank space, the separator for the billionths of seconds is now a dot (".") instead of a dash ("-"), and trailing items after the year-month-day fields may be omitted.

## «enumeration» OsacbmTimeType

```

-OSACBM_TIME_MIMOSA = 0
-OSACBM_TIME_TICK_MICRO = 1
+OSACBM_TIME_POSIX = 2
+OSACBM_TIME_SYSTEM_TICK = 3
  
```

## EngUnit and Enum Type



## EnumValue

```

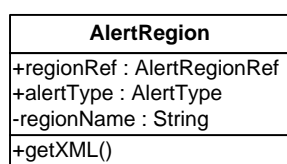
+value (see note) : int
-name (see note) : string
-enumEU : EngUnit
  
```

Enum value is uniquely identified by Eng Unit plus value  
Name may be transmitted optionally.

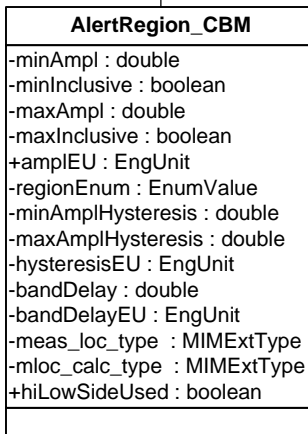
OutPort should have corresponding EngUnit to transmitted value. Therefore in a DataEvent transmission the DataEvent id can link to EngUnit from the OutPort and only a value may be needed in the actual DataEvent if shortness of expression is desired.

## Alerts and Regions

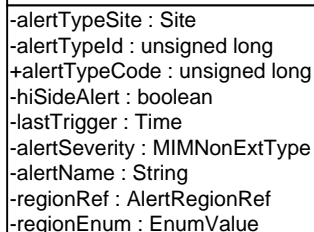
regionId is a unique region identifier for the Site



AlertRegionId is an extensible type to allow for future growth in describing what should cause an alert.



### NumAlert



NumAlert carries with it information about

- (1) AlertType directly from AlertRegion
- (2) Optionally Time when AlertType was first entered.
- (3) Optionally region id for direct tie to the region
- (4) Optionally enum value associated with region

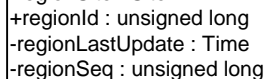
Simplest usage is simply to use

- 1) alertTypeCode set to predefined values
- 2) OSA CBM convention is for unused alertTypeId to mean alertTypeId = 0 which should be based on platform Site
- 3) OSA CBM convention is for unused alertTypeSite to mean use the Site found in the DataEventSet class

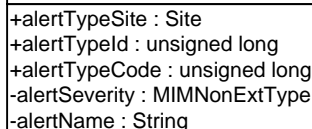
The DataEventSet Site is typically the platform Site. Thus unused alertTypeSite and alertTypeId corresponds to a MIMOSA database id of (platform\_site, 0)

4) Optionally hiSideAlert and lastTrigger are very useful

### AlertRegionRef



### AlertType



## Usage Concept

A set of AlertRegions will be associated with a specific OutPort. The value that associated with the AlertRegion set is the one contained in the DataEvent being output.

When the value contained in a DataEvent activates an AlertRegion the DataEvent will contain a NumAlert associated to the AlertRegion along with the time of occurrence stored in the lastTrigger. In a cbm monitoring system, the following DataEvents from that OutPort will have new values and new times. However, the NumAlert will remain the same while in that region. This includes the lastTrigger time which may be used as an indicator of how long a particular region has been in effect.

When a Region is first entered it gives the specific DataEvent an "Alert Status". For cbm modules supporting "Alert Status" functionality, the output can be suppressed to output only when an alert trigger occurs. This mechanism requires one of the connected type interfaces.

(RegionId, OutPort handle) can be the identifier used by a higher module to control threshold levels via a user defined ControlVector. Future versions of the standard will begin to create a standard UML/XML form for this control.

## Hysteresis BandDelay

Hysteresis and BandDelay are used to reduce threshold nuisance crossings. Region is activated when

- 1) Threshold amplitude is crossed when no BandDelay and no Hysteresis
- 2) Threshold amplitude is crossed for more than BandDelay time
- 3) Threshold amplitude is crossed by more than Hysteresis value
- 3) Threshold amplitude is crossed by more than Hysteresis value for BandDelay

## Hi-Low

hiLowSideUsed default is false. MIMOSA OSA EAI does not presently have it and therefore it would be false for OSA EAI apps

The simplest method of use is to have a single set of alertRegions for an output and a direct set of alert types for those regions. The system should be set up so that AlertTypes and AlertRegions are all unique to the system and within the system. Then only a single int is needed to identify a code, the RegionId and the AlertTypeCode respectively. The Alert classes are based on the MIMOSA OSA EAI CHRIS. Substitute the term Alert for Alarm. The OSA CBM version has a few extra parameters like those for hysteresis and hiSideAlert indicator.

The main principles for optional arguments are:

For those terms that are primary keys in CHRIS: if they are not used, then they should be elsewhere in the information schema, i.e. is Sites is not specified use the site found in DataEventSet. For those terms that are not primary keys, like name, they may simply be expected to be found in a database somewhere has it. In short assume that they are not needed for an operational monitoring system and would only make the system less efficient.

Data class for user definable types

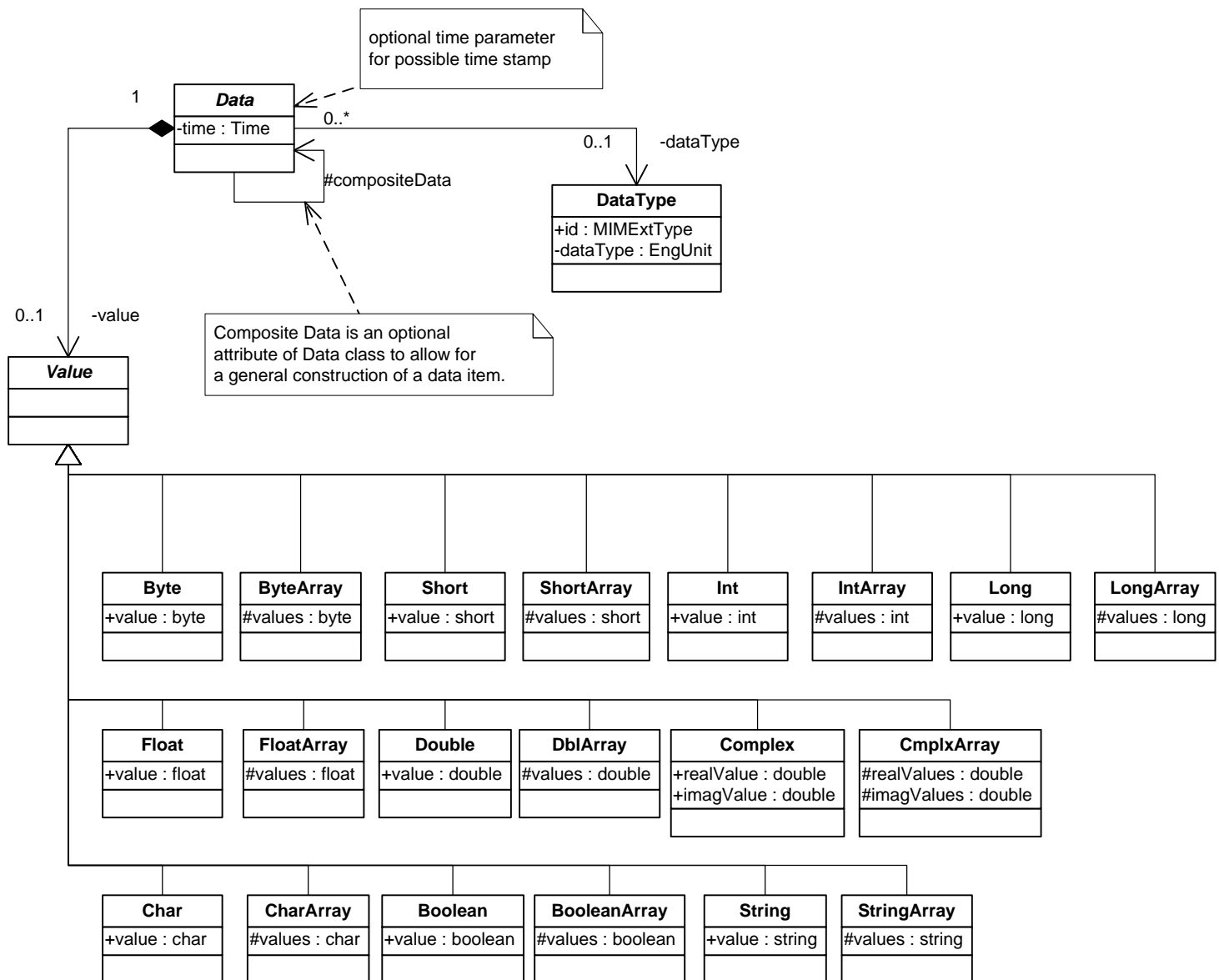
Data is mainly for user definable types not in the OSA CBM specification. This class set should be used mainly as a last resort. Please report any required use to the OSA CBM technical subcommittee.

It is preferred that if there exists an information class that can contain your data is in OSA CBM then that should be used.

It is under consideration to have this removed if no valid use can be found.

The BLOB class is a more standardized and supported approach to sending data types that are not directly in the OSA CBM specification.

Additionally new types, such as multidimensionaly arrays, like wavelets can be added to the OSA CBM specification fairly quickly.

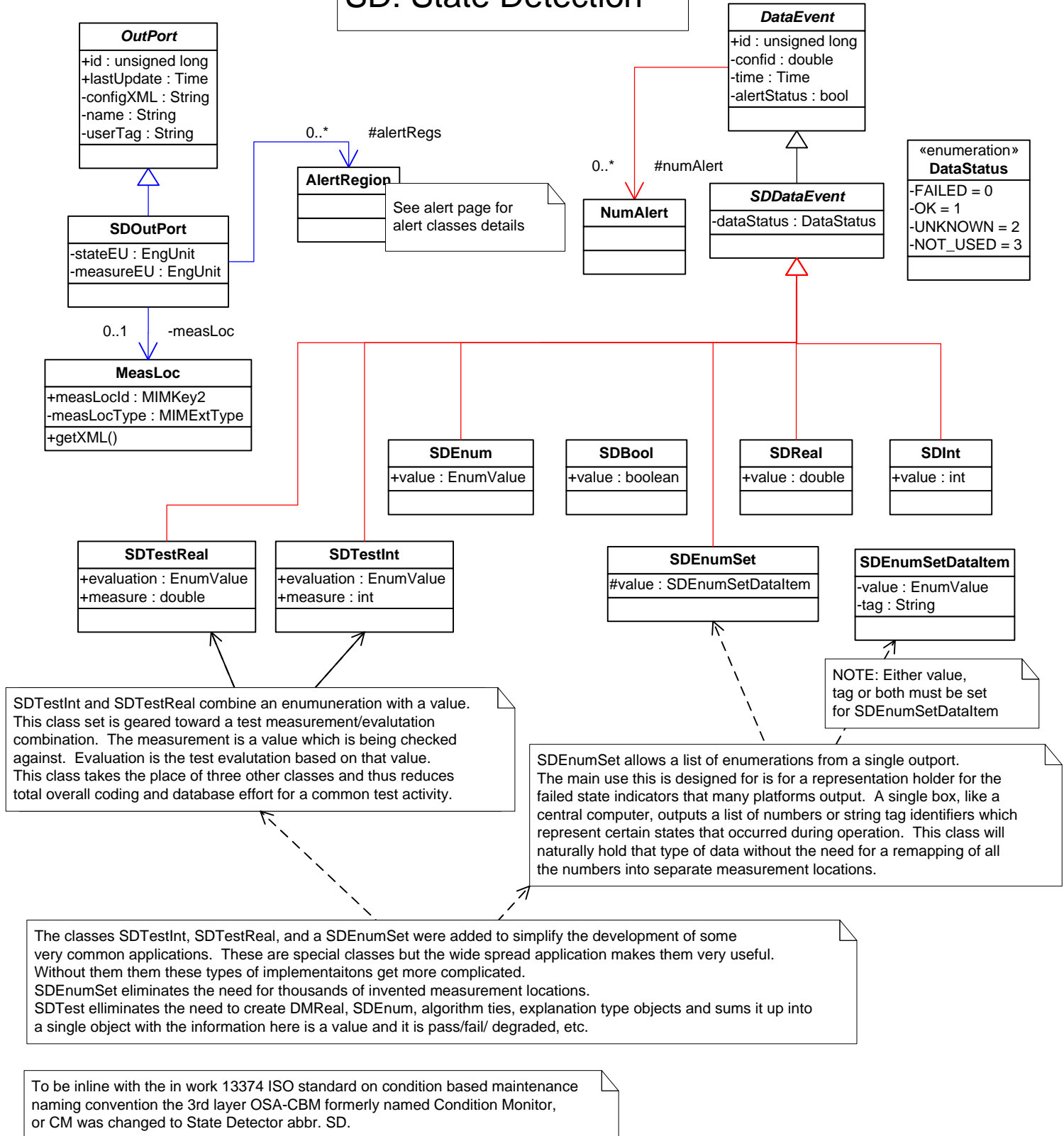


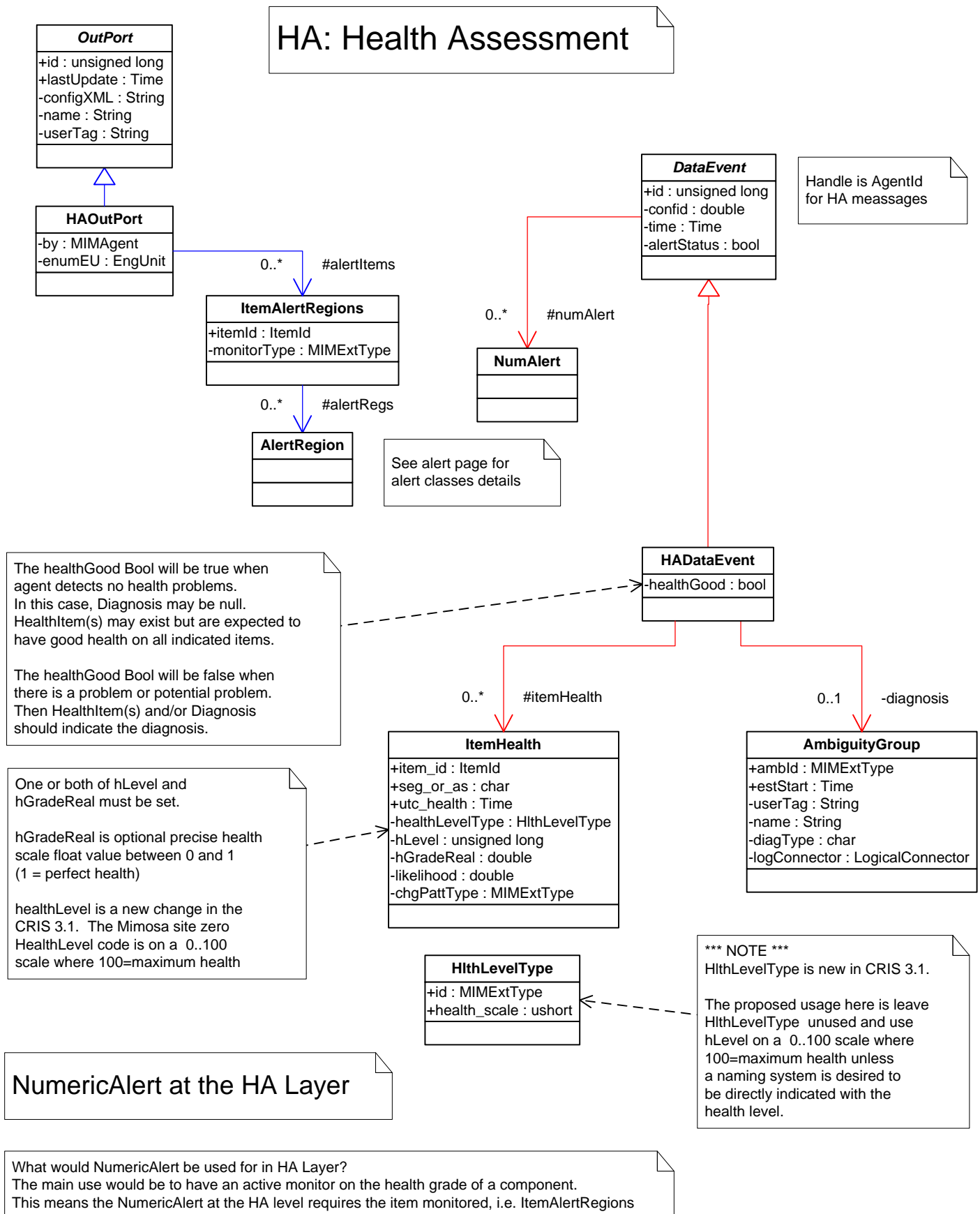


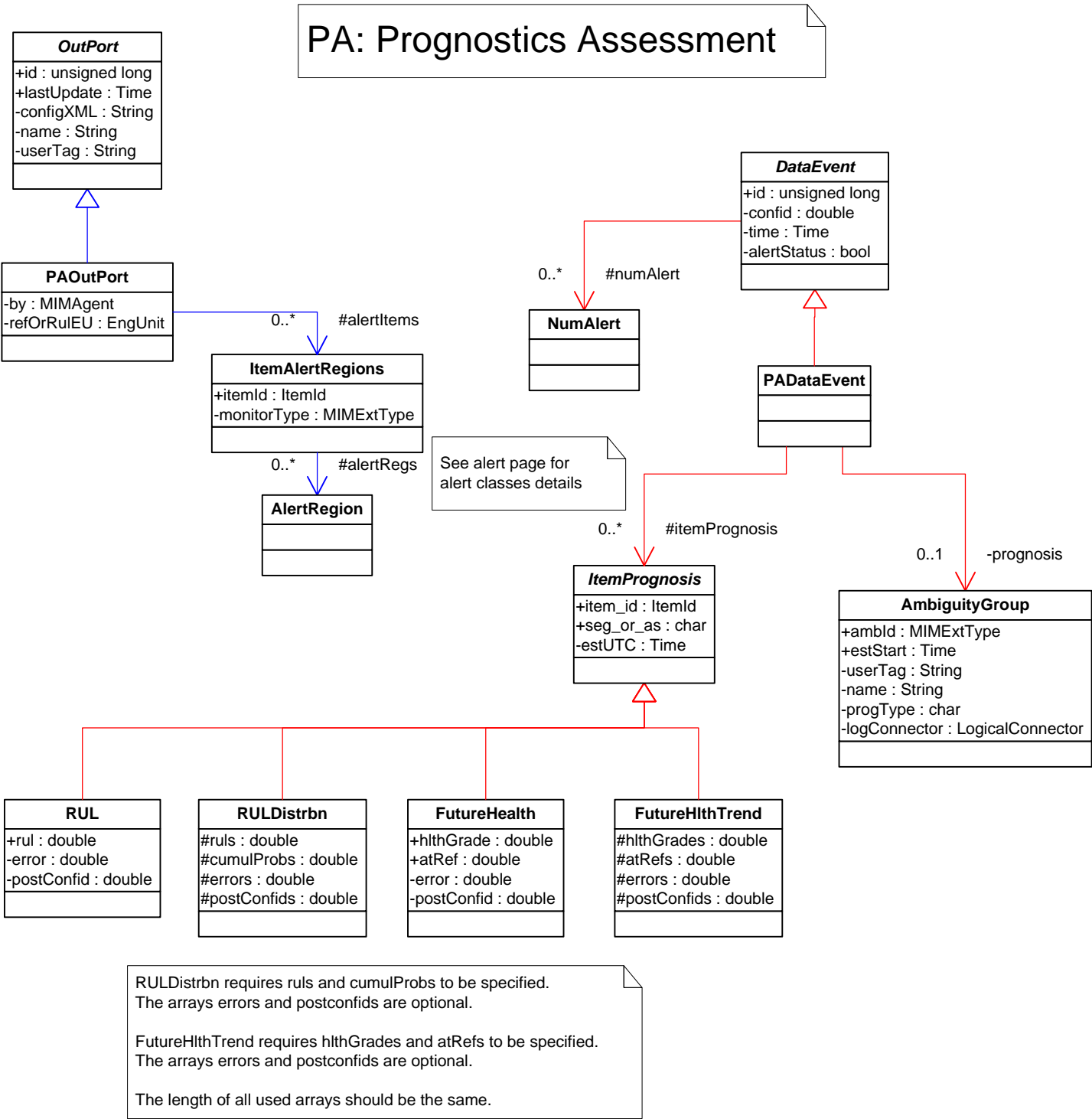




## SD: State Detection

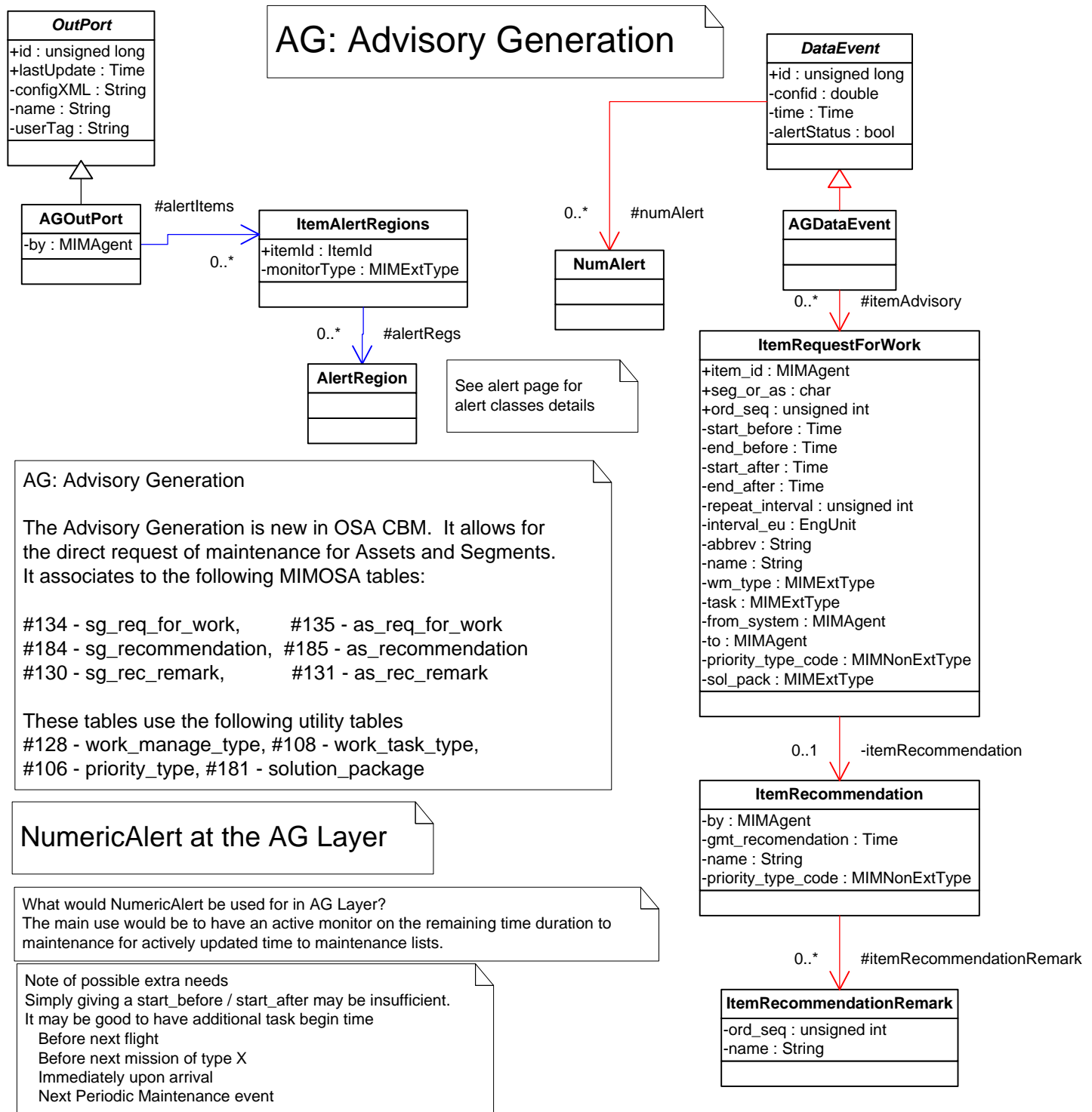






## NumericAlert at the PA Layer

What would NumericAlert be used for in PA Layer?  
The main use would be to have an active monitor on the RUL or FutureHealth hlthGrade of a component. This means the NumericAlert at the PA level requires the item monitored.



## Start of Note Pages

This pages ends the UML specification  
and starts the notes pages for OSA CBM.

## Notes

## XML Extensibility Concept

Extensible type classes are for application specific purposes. IVHM applications may require these specific categories of information for setup and control. These classes allow for a standard way to input and output application specific XML. The getXML is a suggested method for a parent wrapper class.

The main concept is to have a class that is closed to modification but extensible to users. The XML string is used as the conveyor of data.

Implementations should have a getXML(...) method to retrieve a transmittable XML form.

Specific Implementations can use the specific form class structure.

MeasLoc is the Generic Form class.

Other examples of Generic Form classes are: ControlChange, AppNotify, and AlertRegion. Some generic forms may require attributes that are expected for all such specific forms.

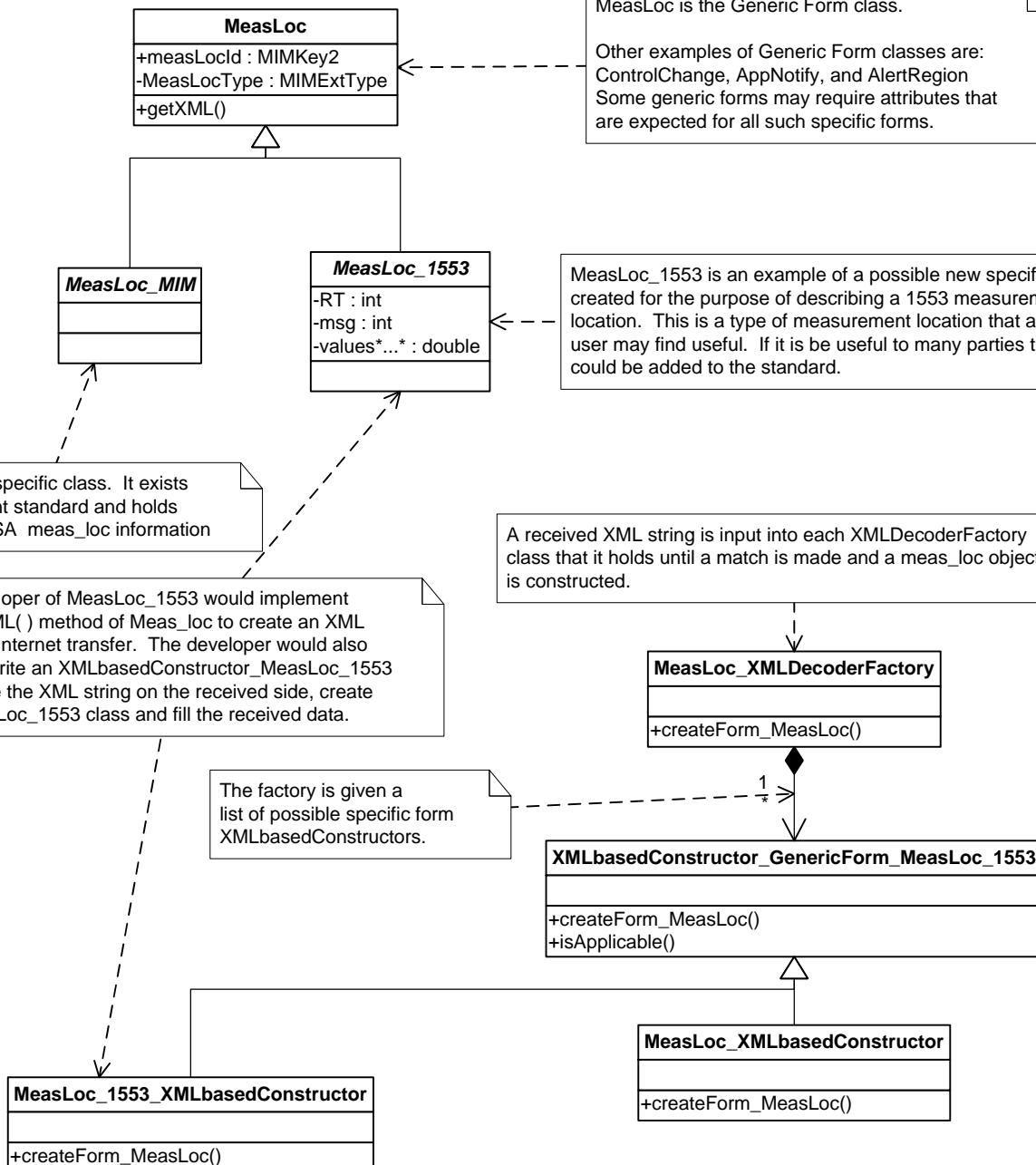
MeasLoc\_1553 is an example of a possible new specific class created for the purpose of describing a 1553 measurement location. This is a type of measurement location that a particular user may find useful. If it is to be useful to many parties then it could be added to the standard.

MeasLoc\_MIM is a specific class. It exists as part of the present standard and holds the standard MIMOSA meas\_loc information.

The developer of MeasLoc\_1553 would implement the getXML() method of MeasLoc to create an XML string for internet transfer. The developer would also have to write an XMLbasedConstructor\_MeasLoc\_1553 to decode the XML string on the received side, create the MeasLoc\_1553 class and fill the received data.

The factory is given a list of possible specific form XMLbasedConstructors.

A received XML string is input into each XMLDecoderFactory class that it holds until a match is made and a meas\_loc object is constructed.





## Mapping Methodologies

### Mapping Methodologies

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The goal is to have OSA-CBM map totally seamlessly into OSA-EAI. The grand picture is the following.

1. Simple 1-to-1 information component mapping.
2. OSA-CBM extensions to CRIS that have extra information that OSA-EAI does not need.
3. A mapping document where difficult mappings or mappings that have many potential solutions are specified to be done in only one way

The following provides a quick overview.

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Perhaps 90% or more of OSA-CBM will mapping directly into OSA-EAI with ease.

There will be some changes and additions in OSA-EAI to facilitate the mapping also.

However there are certain differences and some OSA-CBM needs which are to be handled by OSA-CBM extensions in the MIMOSA specification.

The main requirement for the extensions deals with the ability to get data out of database storage in the original OSA-CBM format with all class structure intact and easily retrievable by a generic mechanism rather than having to hard code an expected form for a particular known configuration

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Main areas for the extensions includes

- 1) The OSA-CBM class-type definition specifics.

The ability to know which OSA-CBM class was used to transmit the data.

- 2) OSACBM time stamp based message identification scheme.

In OSA-CBM all messages such as measurement\_events and health\_assessments which includes proposed\_events are identified by agent or meas\_location, time stamp, and item id in the HA and PA layers. OSACBM small signature vehicles are not expected to generate new integer primary key signatures. The ability to do that would require non-volatile memory storage of some form to remember last number used.

Instead, OSA-CBM offers a slightly different primary key basis (agent, time, item).

All the same important information components as those found in OSA-EAI are there.

When such a message reaches a the OSA EAI database location the OSA-EAI proposed event primary key signature may be generated.

- 3) Ambiguity Groups

OSA-EAI (V3.2?) will be enhanced to accomodate amibuity groups.

- 4) Explanation

Explanation is the ability to state connection between data used as input and resultant data.

The OSA-CBM explanation uses references within the OSA-CBM context. OSA-CBM extensions Explantion table will be used by those desiring this information to be retrievable.

OSA-EAI has many data tie tables for those desiring this information tie in the OSA-EAI context.