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OSA-CBM stands for Open System Architecture for Condition Based Maintenance.

This specification is offered by the MIMOSA organization. Information on this organization can be found at www.MIMOSA.org.

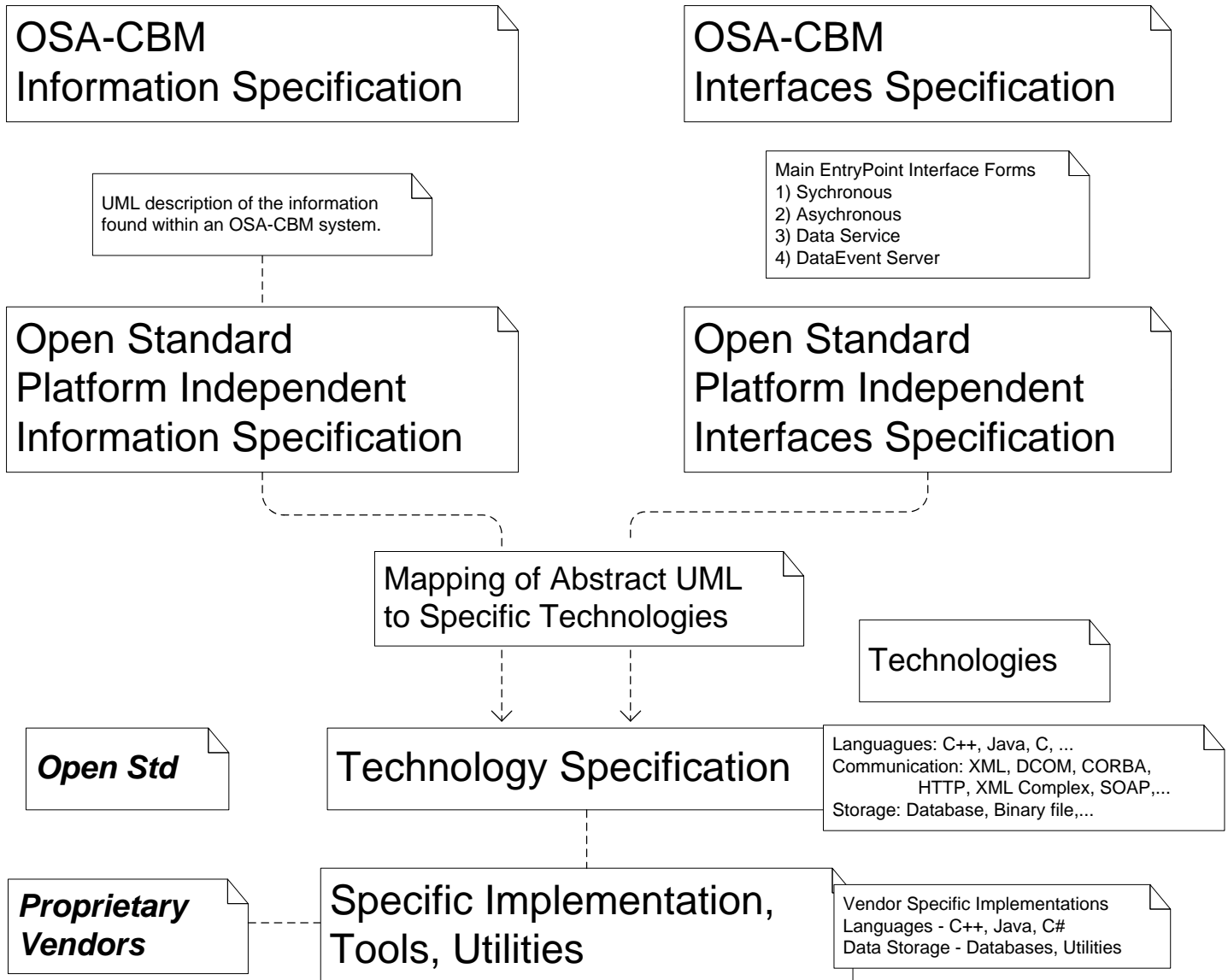
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The version of OSA-CBM 3.1 corresponds to the OSA-EAI version 3.1.

This is the version reference in ISO 13374 which is a CBM standard.

This OSA-CBM is based on the work supported by the Office of Naval Research under Agreement No N00014-99-3-0011 OSA-CBM Boeing DUST. This version has been modified from the original OSA-CBM 1.0 DUST program specification within the MIMOSA organizational process.

These modifications improved the specification in capability and compatibility to the MIMOSA OSA-EAI specification and its advancements.



This specification is designed for multi-technological implementation.

From this point the UML needs specific mappings into programming languages, network protocols, and database storage (e.g. MIMOSA OSA-EAI CRIS). This document covers the abstract UML description of the specification.

This architecture splits the information specification, which defines the information that can be moved around in a CBM system, from the interfaces that can be used to move that information. This separates the information that is moved, stored, and processed from the mechanism that accomplishes these tasks.

An implementation of this technology will select applicable interface(s) and merge the information specification into a complete package.

The information specification and interface specifications as they are created will be found in other documentation.

Specific technological implementations may be vendor IP supplied tools and utilities. Such vendors are encouraged to become MIMOSA members.

Technology Specification

This document covers the OSA-CBM abstract UML specification. It defines the core specification of the information found in a CBM system. The Interface specification offers ways to move this information around.

A mapping effort is required to convert this specification into a technology representation that is verifiable. For example, a mapping of the UML Information Specification to XML will result in an XML schema that specifically defines the XML form of the data. The XML schema will then be used to validate a system that is required to output OSA-CBM XML.

Notes on Compliance

Information Specification versus Interface Specification

The information specification describes the type of information found in a CBM system. (OSA-CBM was developed in close connection with the MIMOSA OSA-EAI CRIS 3.0.) The interface specification describes methods of moving this information around. One development difficulty was that different technologies have different ways of achieving this goal. (For example, there are already existing standard ways of moving XML around.)

The initial goal for the OSA-CBM 3.1 technology mapping is an XML schema for the information content. Application developers may choose an existing technology for moving the XML around.

Compliance will be based on XML conforming to the standard schema.

Interfaces

Interface Types

- 1) Synchronous
- 2) Asynchronous
- 3) Data Service
- 4) DataEvent Server

Why so many interface types? OSA-CBM is a specification that covers a broad technological base. The main aspect of value for OSA-CBM is its information specification. That information specification was designed with concepts in mind as how to map it to programming languages, transfer protocols, and data storage devices.

There are several interface types that are required for wide standard applicability. Each technological implementation will likely not implement every interface. Rather, the technology of choice will typically select the interface(s) by logical choice.

Example: A Web server returning XML over HTTP is Synchronous - Stateless.

Definitions

Interface

An Interface describes how information will be moved.
A request is made to get information from an object.
A notify is made to input information into an object

EntryPoint - the interface presented by an object to the outside world.
It provides direct access to the top level classes.
(For example, the DataEventSet and Configuration classes.)

EntryPointSink - Asynchronous data return path for requested information.

Synchronous Interface - Information is returned by the Request method.

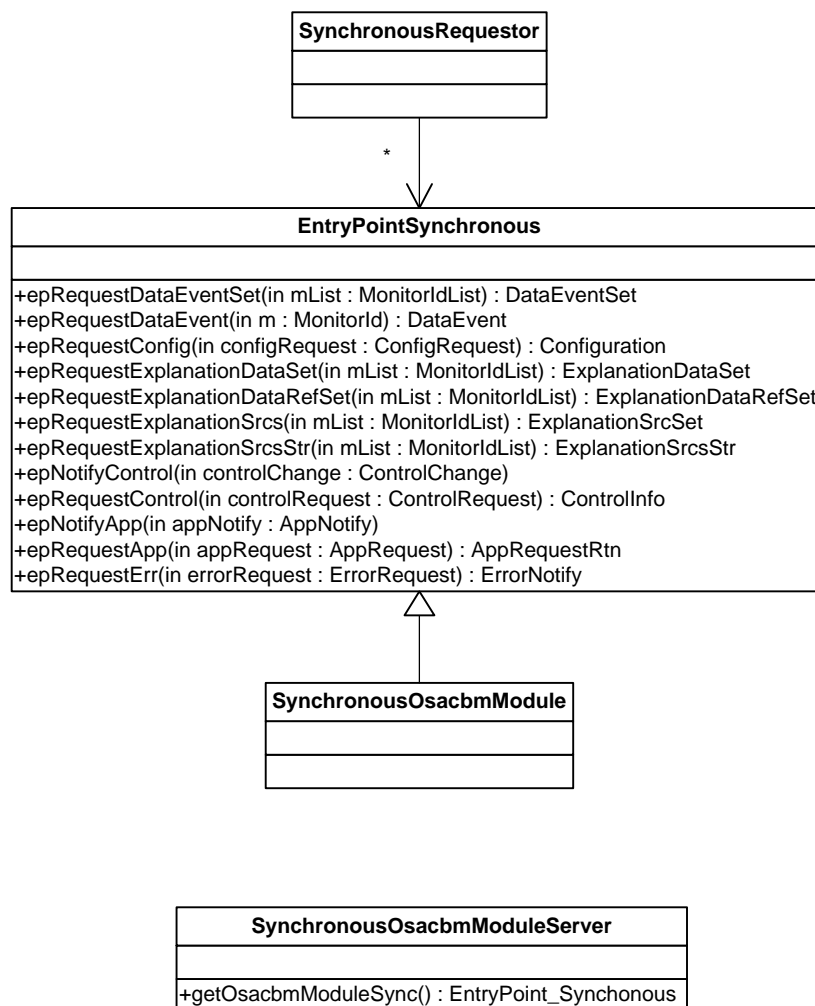
Asynchronous Interface - Information is returned as available via EntryPointSink.

Synchronous Interface

The synchronous interface returns data with the call.
It models the Web XML over HTTP fetch methodology

Example:

```
newData = moduleEPptr->requestDataEventSet( );
```



The SynchronousOsacbmModuleServer interface is the suggested method
for creating many Synchronous servers for a specific Osacbm Module.

Asynchronous Connected Module Interface

The Asynchronous Interface:

1) Allows for any number of higher modules.

2) Two-way connection is established and maintained for duration of need.

The sinkId and epId are used for specific sink and entry point identification.

The two-way connection has several feature advantages:

2.1) It is typically faster in usage since the overhead of connection occurs only once.

2.2) It allows for three different modes of communication.

2.2.1) Return on request - main OSA-CBM 1.0 style of communication.

2.2.2) Return when threshold is exceeded. The connection can be setup for notification only on threshold crossing.

2.2.3) Push All - The lower module pushes data to the higher connected module for every frame without the need for a request beforehand.

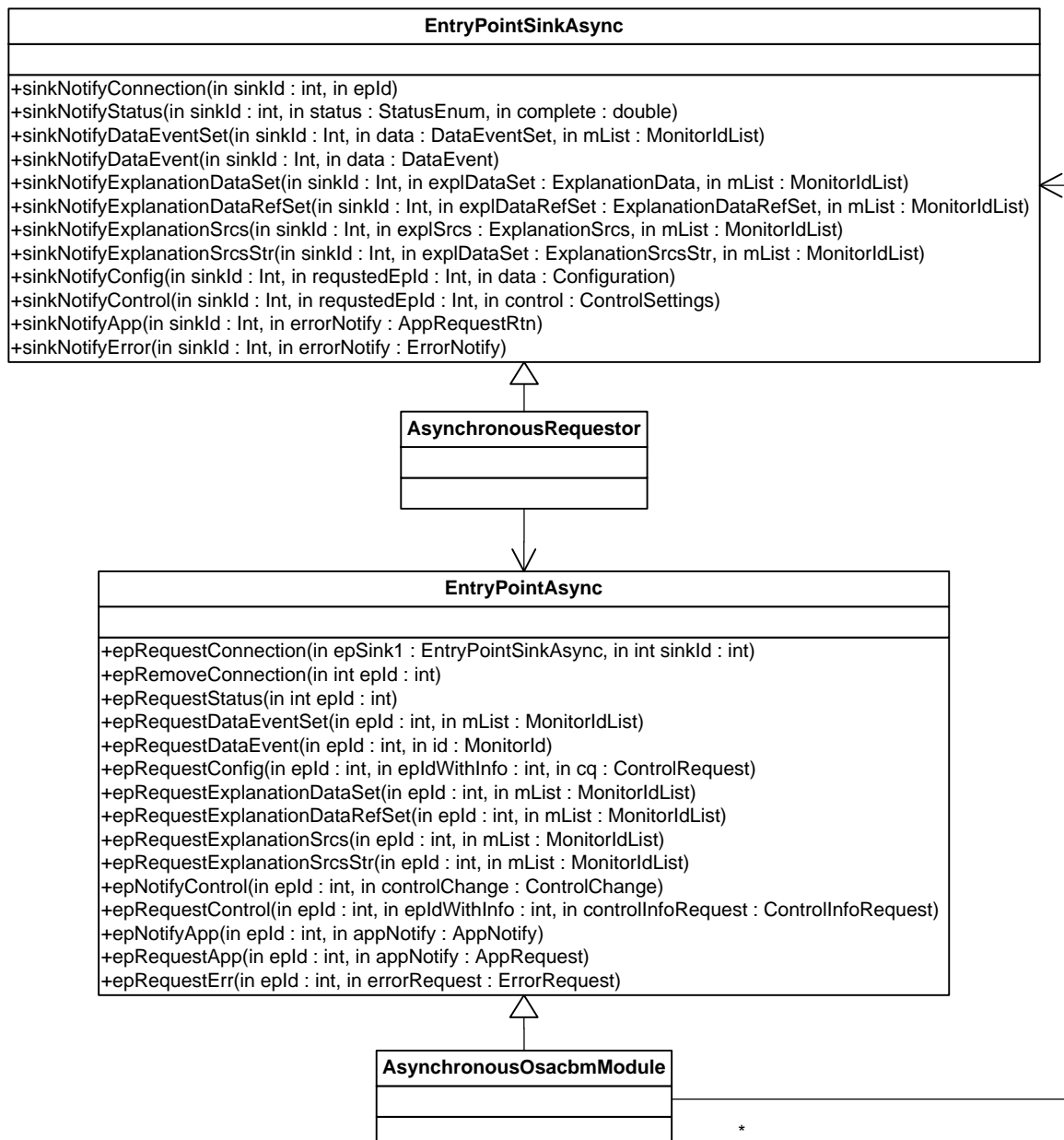
3) Example method call interplay with the connection oriented Asynchronous Interface:

// A higher module requests data from lower module that it previously established a connection with

IpEp_lowerModuleWithData->requestDataEventSet(IpRequestingModuleEPSinkptr);

// The lower module returns data when it is ready

IpSink_higherModule->notifyDataEventSet(data);



Data Service

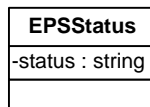
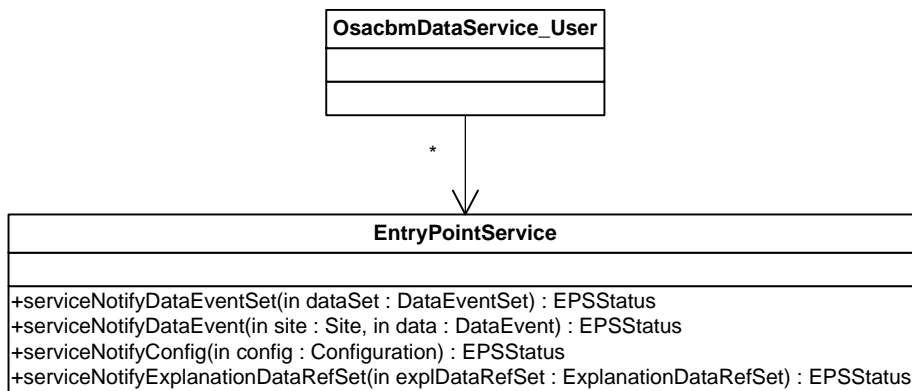
EntryPointService is a one way data input device.

An EntryPointService is a well known location service of a well known function.

Two possible uses would be:

- 1) data storage utility
- 2) maintenance advisory receiver service

The first four methods for DataSet, DataEvent, Config, and Explanation are the main ones expected to be used.



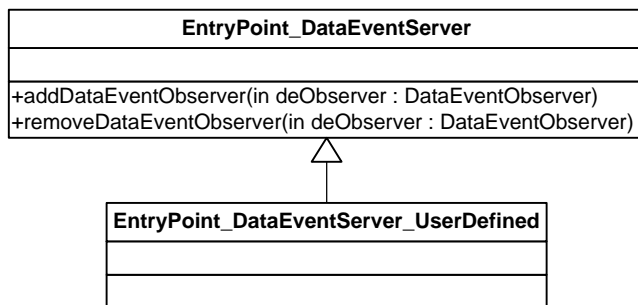
EPSSStatus is a return indicator of how an input message was received.

DataEvent Server

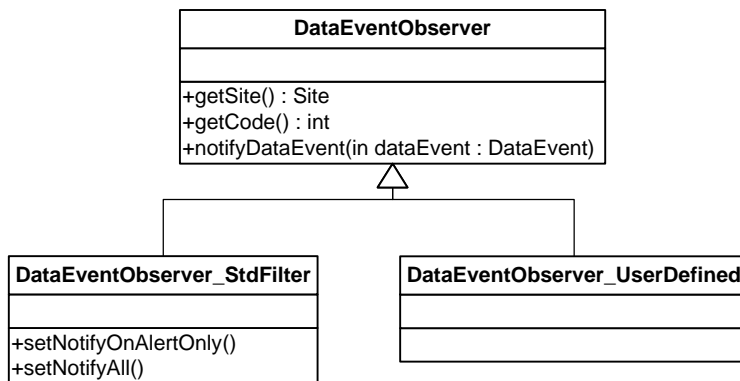
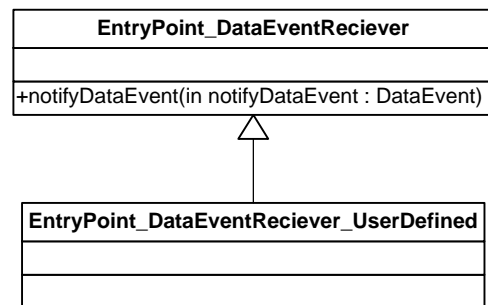
In many systems, signals are moved individually.
This page describes an interface mechanism for handling an individual DataEvent in a very simplified interface.

All UserDefined classes are abstract representations of some class that it written with any desired class name with specifically desired functionality for special handling of signals.

Serving module interface



Receiving module interface



A module that provides DataEvents will inherit from the EntryPoint_DataEventServer.

A module that is to recieve DataEvents will inherit from EntryPoint_DataEventReciever.

The DataEventObserver will contain a reference to the EntryPoint_DataEventReciever and have the notification called by the EntryPoint_DataEventServer when a new DataEvent is ready.

Is is possible to put filtering of events into the DataEventObserver class via a child class. DataEventObserver_StdFilter is designed to all for filtering of DataEvents with alerts only.

Information Specification

The Information Specification describes in UML the information found in a CBM system. This specification was developed in conjunction with OSA-EAI CRIS.

There are six main categories of information:

Dynamic Data	(on platform)
Configuration Data	(not typical for on platform)
Explanation Data	(on platform optional)
Control Data	(simple user option)
App Data	(simple user option)
Error Data	(simple user option)

Each of these is individually addressable in the interface.

There is a request made for a DataEventSet and a DataEventSet is returned. A request is made for Configuration Data and Configuration Data is returned.

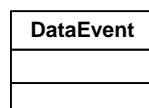
It is suggested that only Dynamic Data is required to be used in embedded systems such as a small platform IVHM system where configuration is static and engineering units are built in. The addition of configuration data especially forces users to put into these systems information not typically found there. That adds development time for something of very limited or no use within its present realm.

For such systems, MIMOSA servers may exist at servicing locations which contain the configuration information.

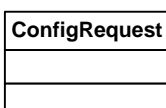
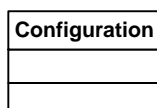
Information Specification - EntryPoint Classes

The EntryPoint interface provides direct access to the following classes. The remaining thrust of this document describes their details in UML form.

Data

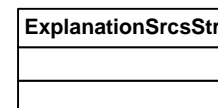
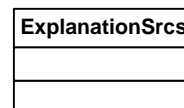
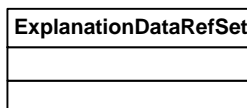
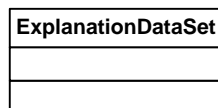


Configuration



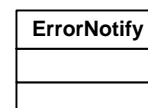
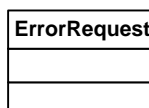
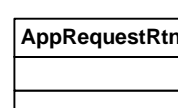
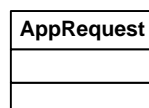
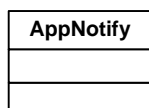
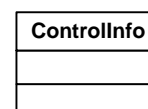
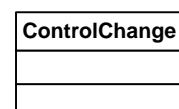
ConfigRequest is an interface input argument used by the requestor to allow possible selection of a subset of the Configuration data to return.

Explanation



Extensible

Extensible types for application specific purposes. Certain applications may require these specific categories of information for setup, control, and error reporting. These classes must be implemented in a way that is open to extension by child class hierarchy.



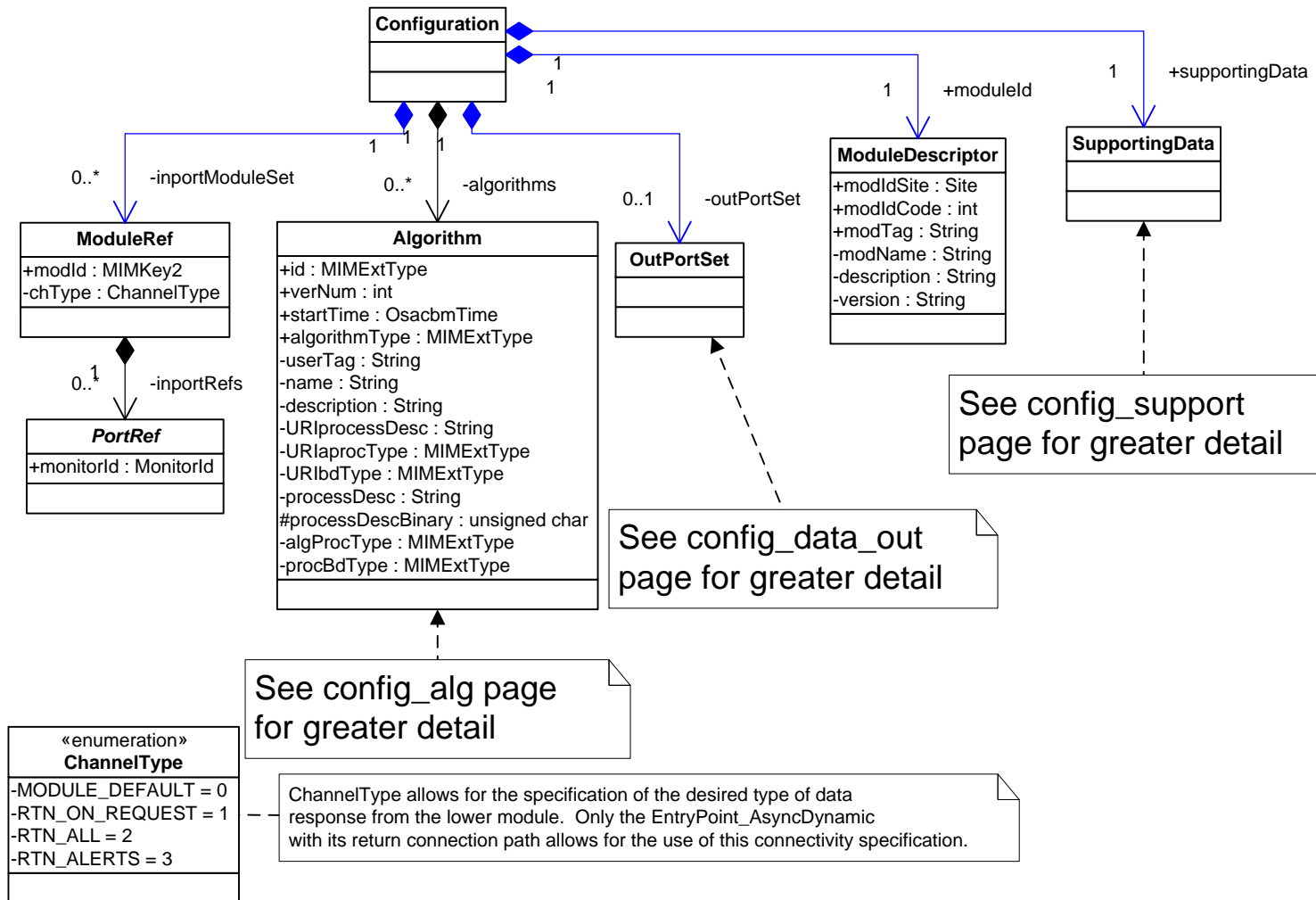
Legend

— organizational	— dynamic data	— general
— configuration	— explanation	— control
- (dash) is for an optional parameter	+ (plus) is for a non-optional parameter	# (pound) is for array parameter

The Legend explains some of the OSA-CBM specific nomenclature. Note especially the '-', '+', and '#' used to indicate parameter optionality and count.

Configuration

Configuration gives information about an OSA-CBM module's input sources, description of algorithms used for processing input data, a list of outputs, and various output specifics such as engineering units, thresholds for alerts, etc.



InportModuleSet gives information about where a module gets data from.

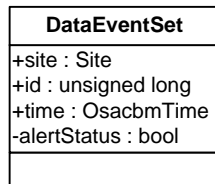
Algorithm describes the process used to generate a DataEvent.

OutPortSet lists each OutPort. An OutPort is a 'data channel' and the OutPort class gives specific configuration data for that data channel.

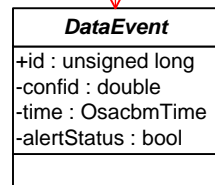
Supporting data gives additional information about MIMOSA MIMKey or primary key references which may be used elsewhere in this architecture.

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DataEventSet



1..* #dataEvents



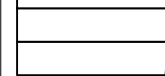
OutPort contains configuration/meta information about a specific DataEvent 'channel'. The attribute id equates to a MIMOSA meas_loc_id (DA,DM,SD) or agent_id (HA,PA). The id along with Site specified in OutPortSet forms a complete MIMOSA meas_loc or agent primary key identification set.

OutPortSet is optional but any application that wants or requires strong meta information, such as Eng Units should use it.

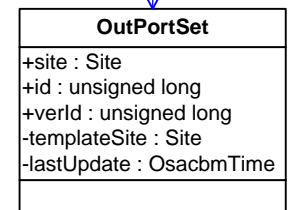
The id used by a DataEvent will be the same as the id used by the associated OutPort. A system that serves DataEventSets should keep array order constant.

OutPortSet

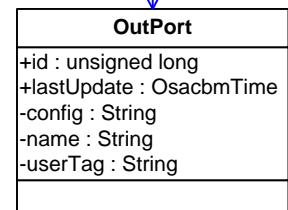
Configuration



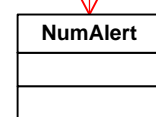
0..1 -outPortSet



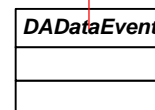
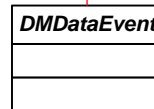
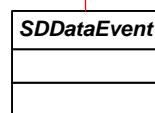
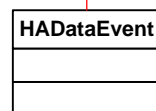
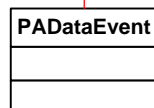
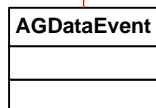
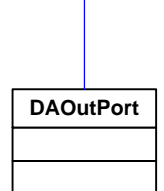
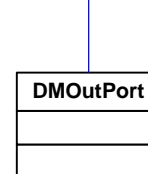
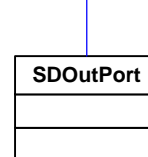
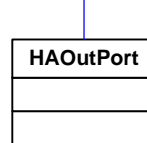
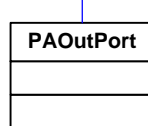
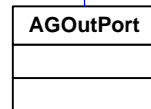
#outPorts 1..*



0..* #numAlerts



See Alert page for greater detail. NumAlert has meta information contained in the AlertRegion and ItemAlertRegion



Note: AlertRegion is used by DAOutPort, DMOutPort, and SDOutPort.

ItemAlertRegion is used by HAOutPort, PAOutPort, and AGOutPort.

DataEvent contains the data for one OutPort data generation event.

The DataEvent child hierarchy below it is associated with a particular layer in the OSA-CBM architecture. Those classes have child classes below them describing a particular data type.

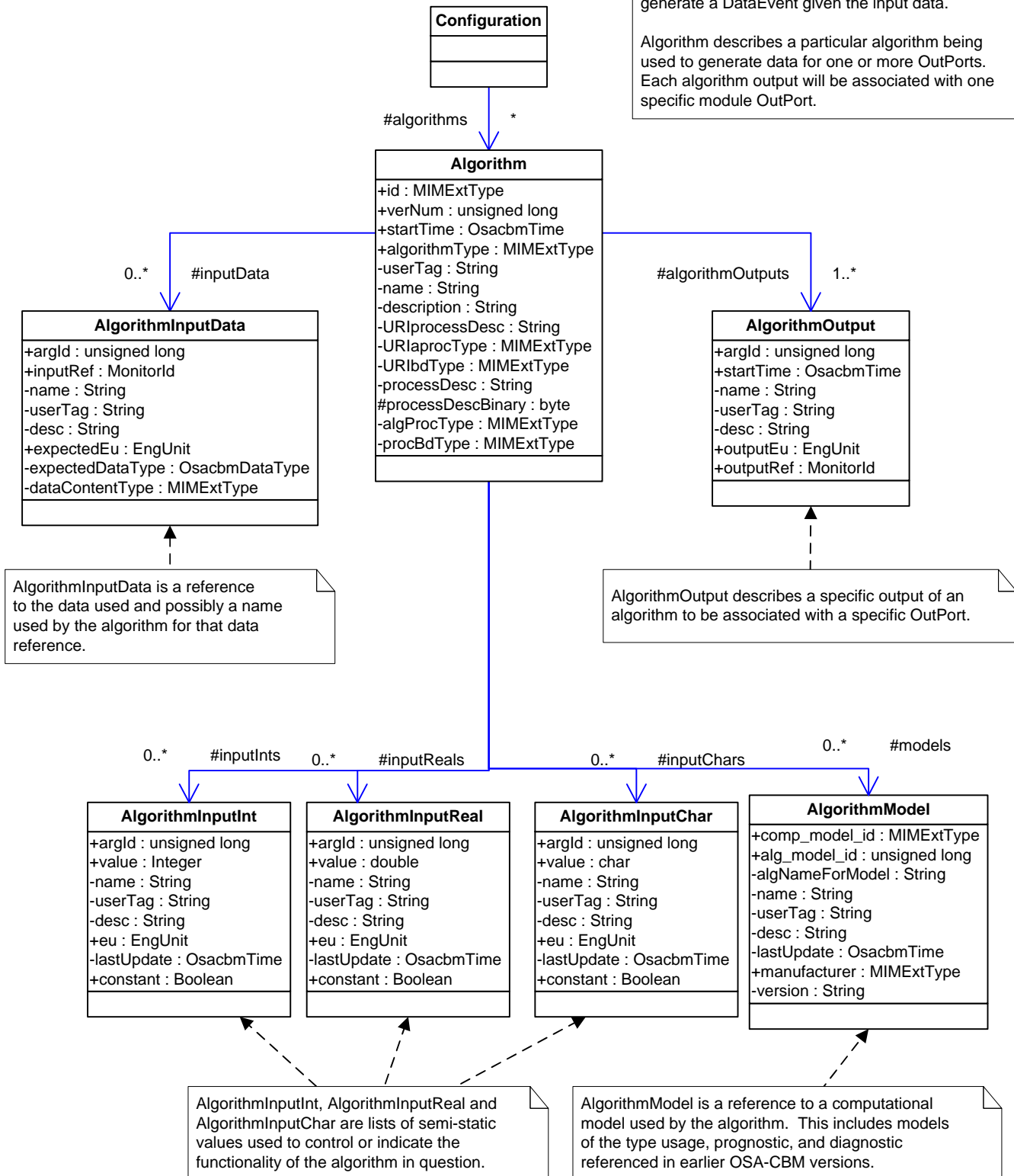
OutPort contains the configuration information specific to one output channel of a module. The OutPort child hierarchy associates to a particular layer in the OSA-CBM architecture.

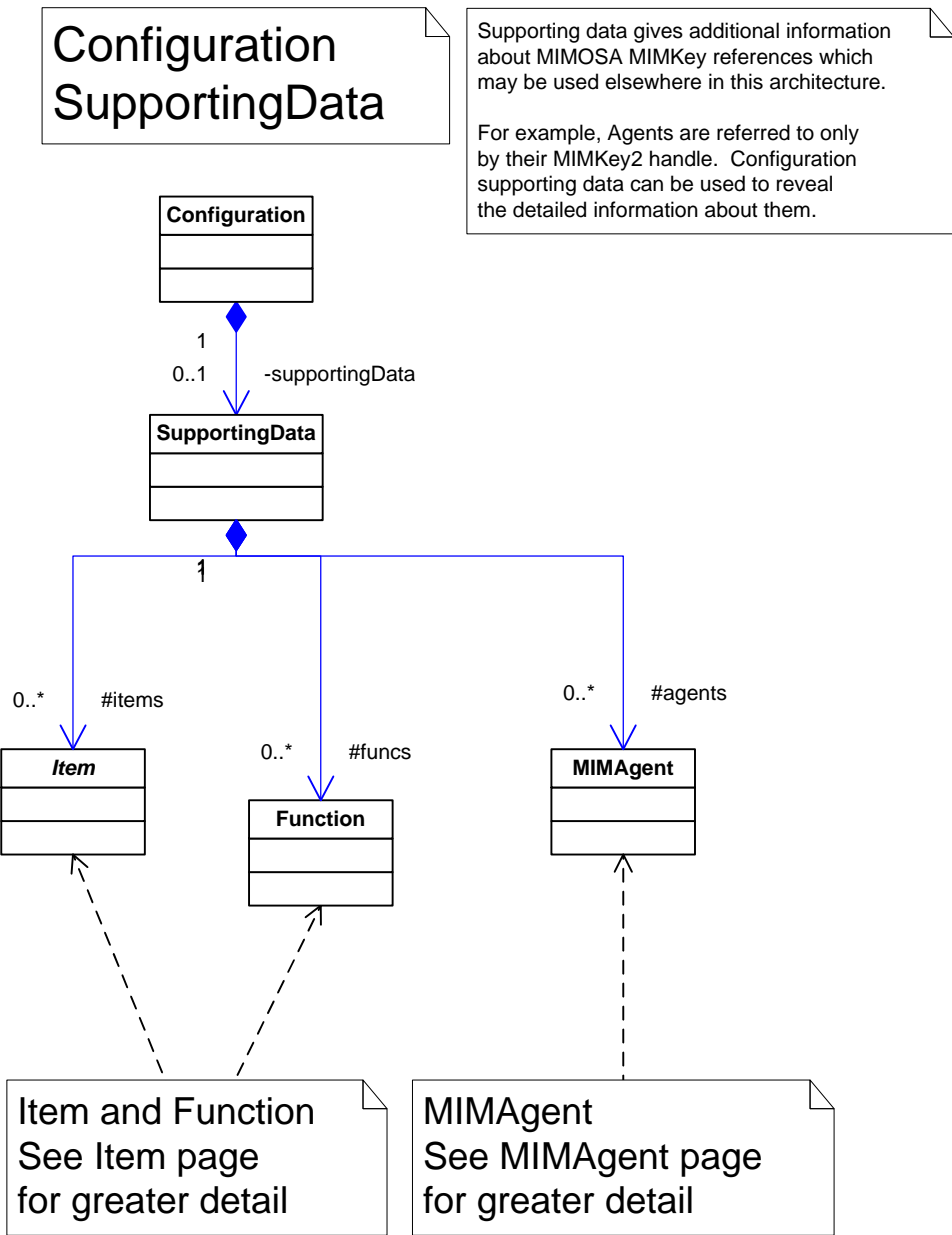
Time on DataEvent is optional. If it is used it is meant to override the time from DataEventSet. It is also used with single DataEvent fetching.

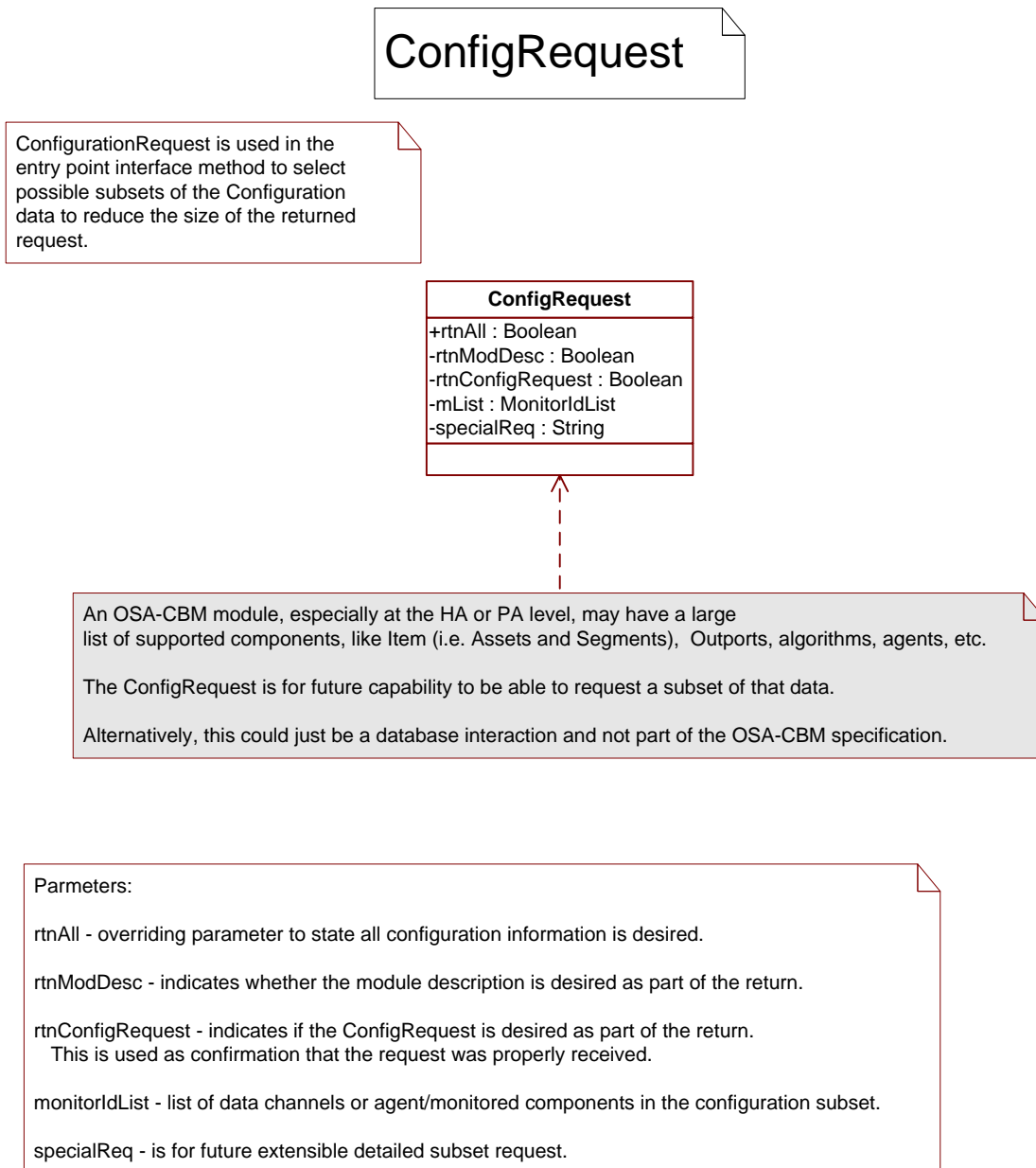
Configuration Algorithm

Algorithm describes the process used to generate a DataEvent given the input data.

Algorithm describes a particular algorithm being used to generate data for one or more OutPorts. Each algorithm output will be associated with one specific module OutPort.







Explanation

Explanation is the Data or a Reference to the Data used by a module to produce an output.
The OutPort algorithm is a description of that process.

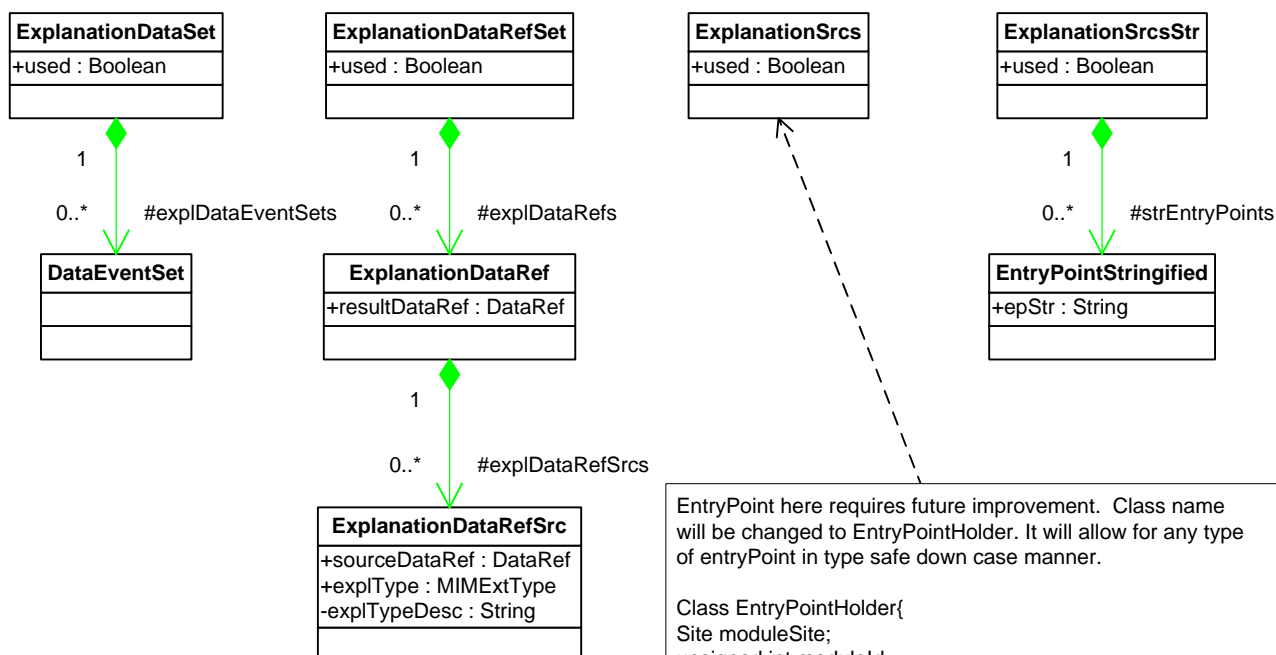
Explanation consists of four possible necessary forms depending upon the application.

The first is simply the data used for a calculation.

The second is more of a handle / timestamp type of reference to the data used. This is used when the data comes from a well known location or it is known to be stored somewhere. The main example is using data stored in a database.

The final two forms are two different ways of giving direct access to the modules supplying the data. One is a set of direct pointers to modules. The other form is a "stringified" form of a pointer that will allow a user to construct a pointer to the module.

Explanation Forms



There will be many types of standard MIMOSA OSA-CBM explanation types.

Note on "used" boolean

Note, if a form is not used, then just set the boolean 'used' to false and return an empty set.

EntryPoint here requires future improvement. Class name will be changed to EntryPointHolder. It will allow for any type of EntryPoint in type safe down case manner.

```

Class EntryPointHolder{
    Site moduleSite;
    unsigned int moduleId;
    EntryPointType epType; // MIMNonExt
};
  
```

```

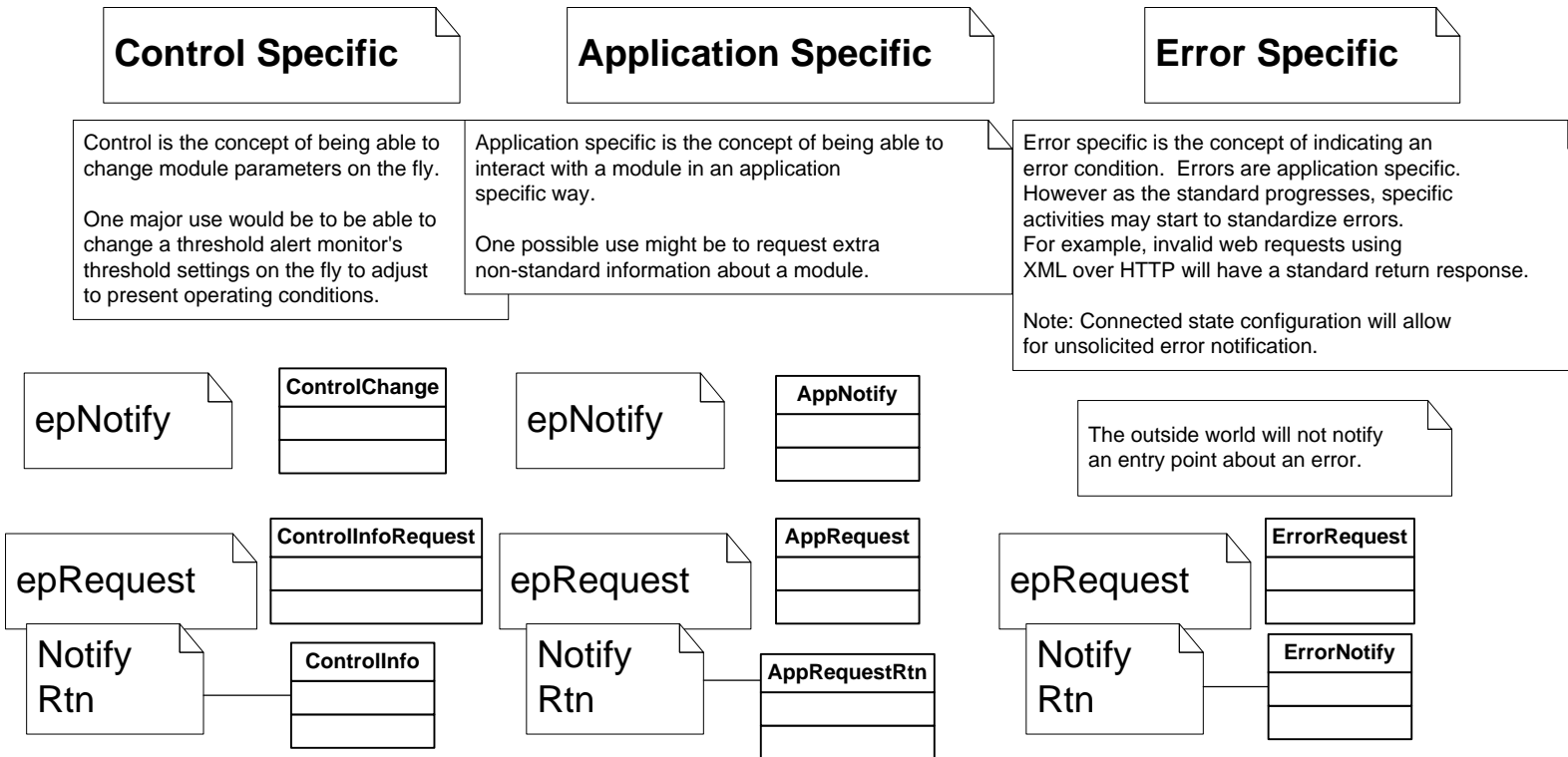
Class EntryPointHolder_Type1:public EntryPointHolder{
    EntryPointHolder_Type1& ep;
};
  
```

Extensible Components

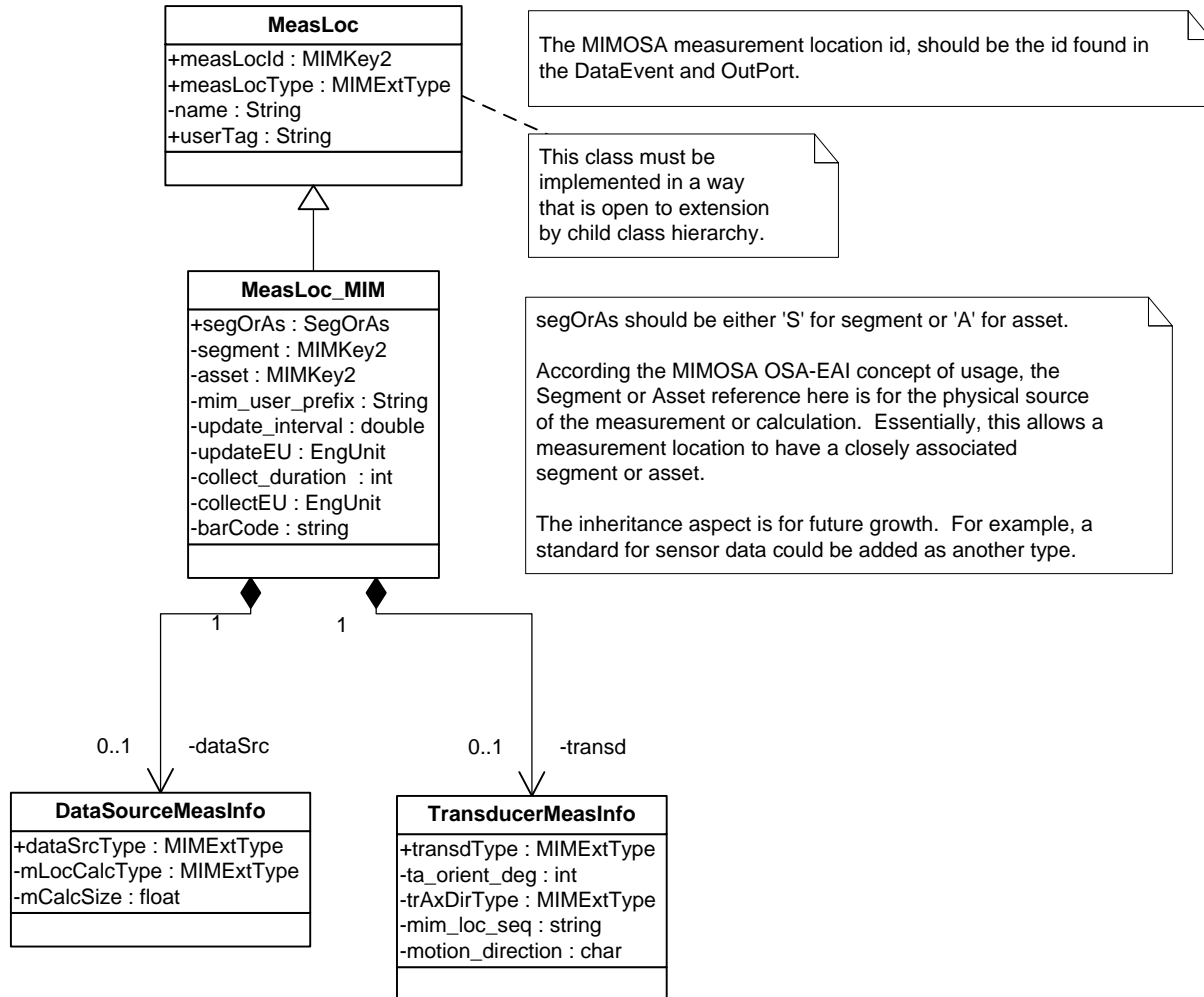
These are called the extensible components because they are very application specific.

A specific use may be designed with UML and have a XML mapping. A specific language implementation may use the UML class form. Any serial communication needs, like HTTP, DCOM, or CORBA over Ethernet, may then convert the UML into the XML form and use the standard interface without the need to develop another communication interface.

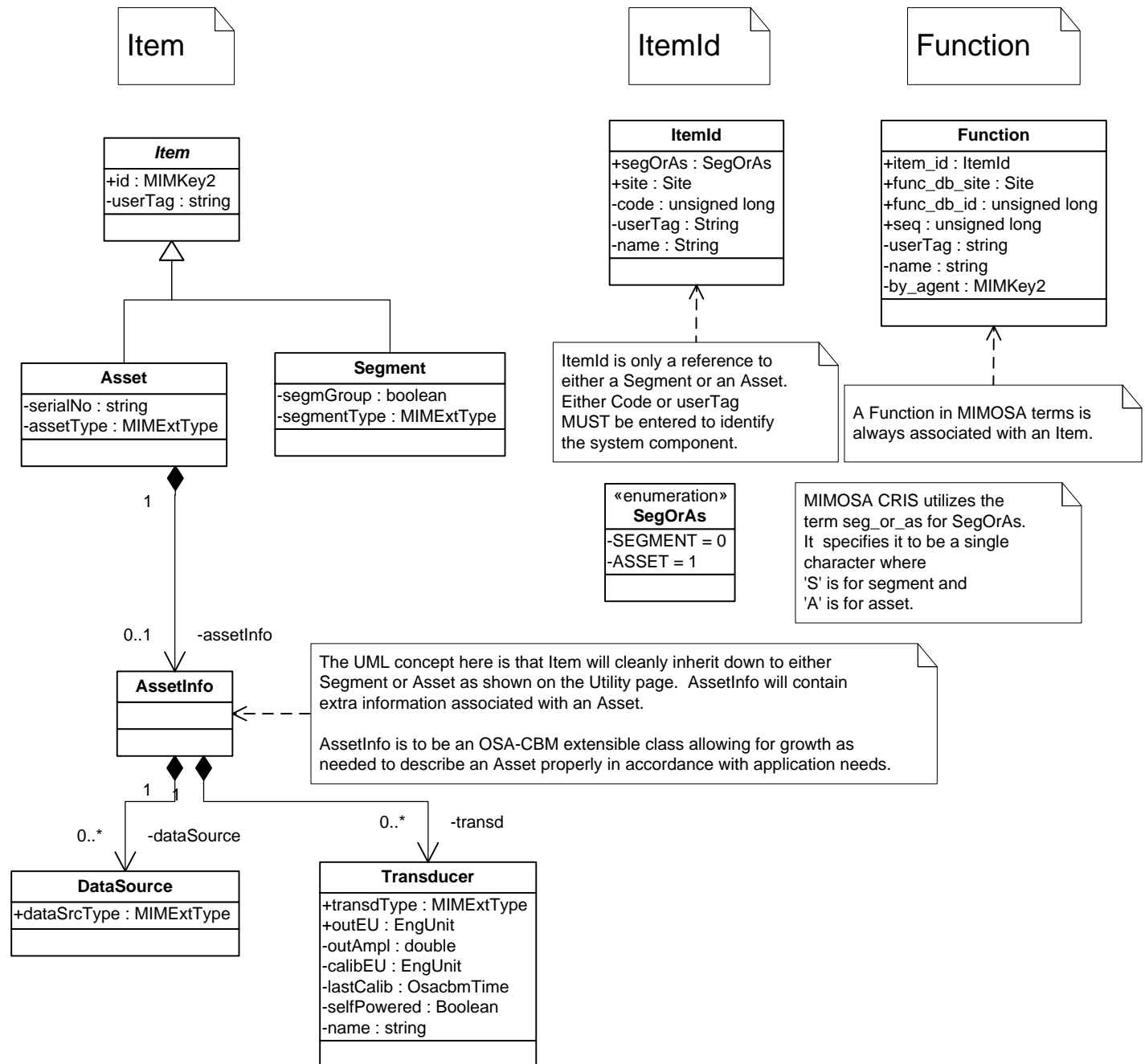
Note once again, these are application specific!
It is fine if a small embedded system does not want to use them or wants to use them in a very narrowly defined way.



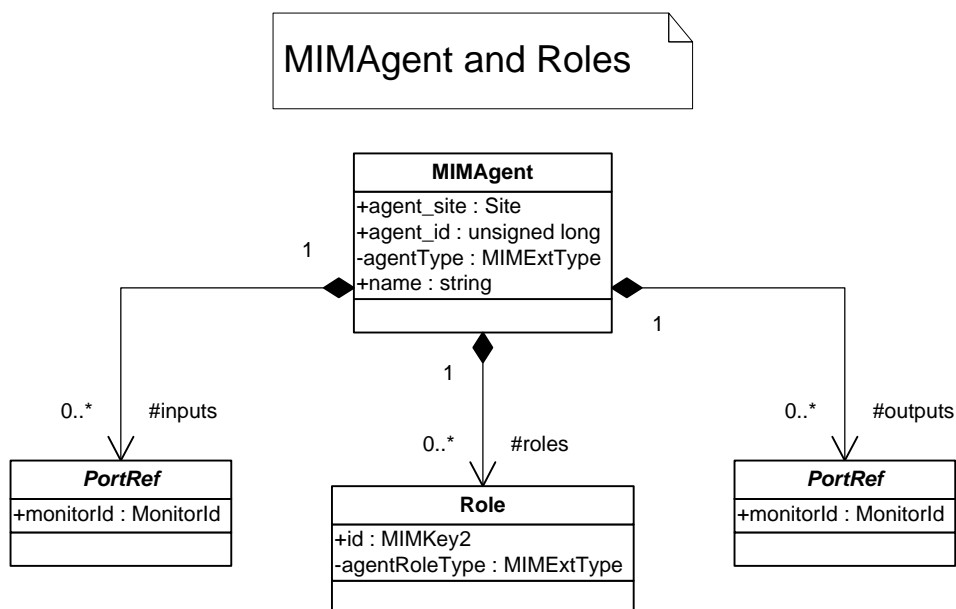
Measurement Location (DA, DM, SD)



The Item page details the Item and Function classes that may be used or referenced elsewhere in this document.



This page details the MIMAgent class that is referenced elsewhere in this document.

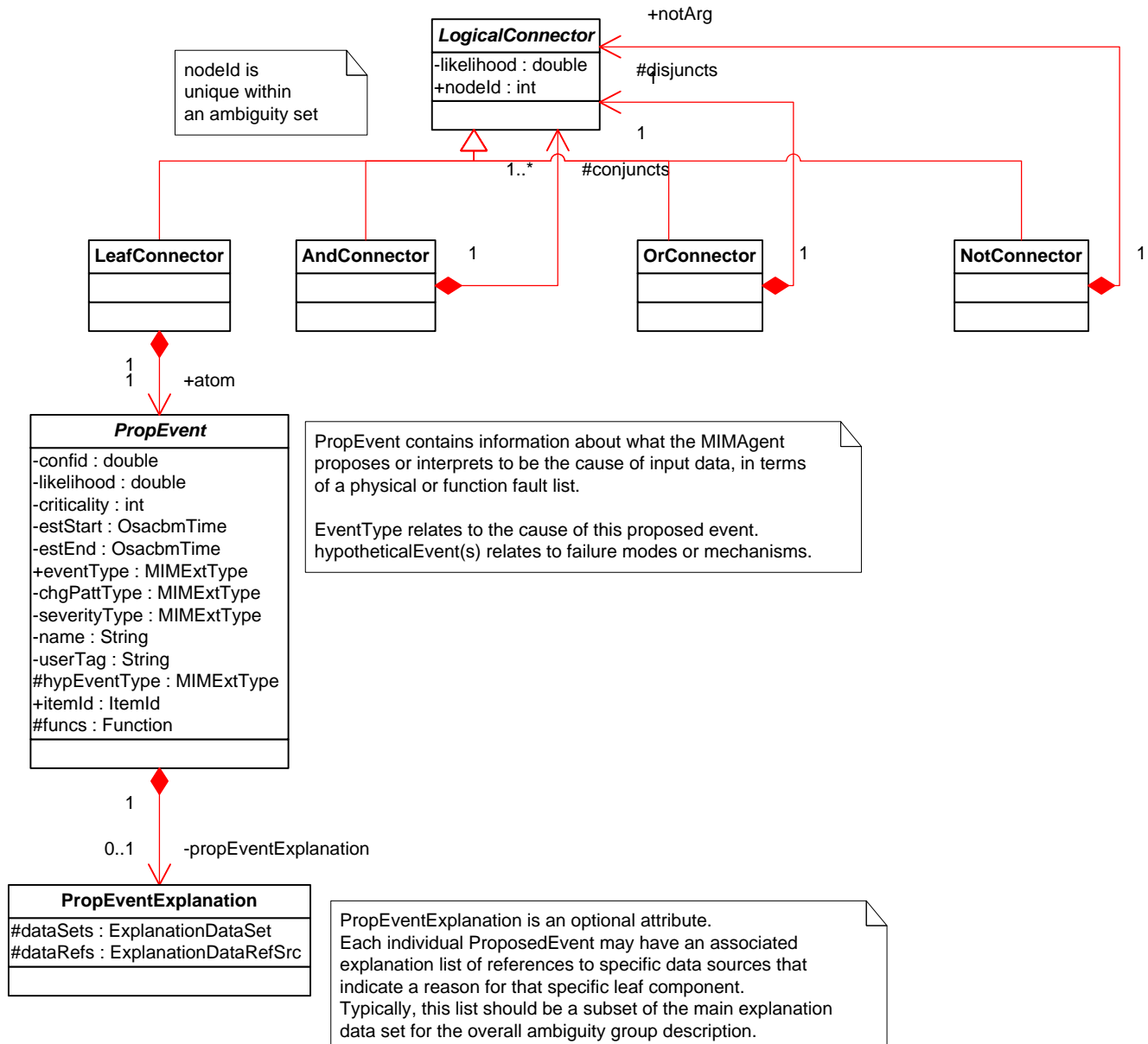


Proposed Event for Failure Descriptions (HA,PA)

The LogicalConnector provides for any style of ambiguity group by using combinations of the AndConnector, OrConnector, and NotConnector classes.

The LeafConnector class gives information about the proposed event fault.

A single LeafConnector without using the And, Or, and Not Connectors is the simplest form used to describe a single determined fault.



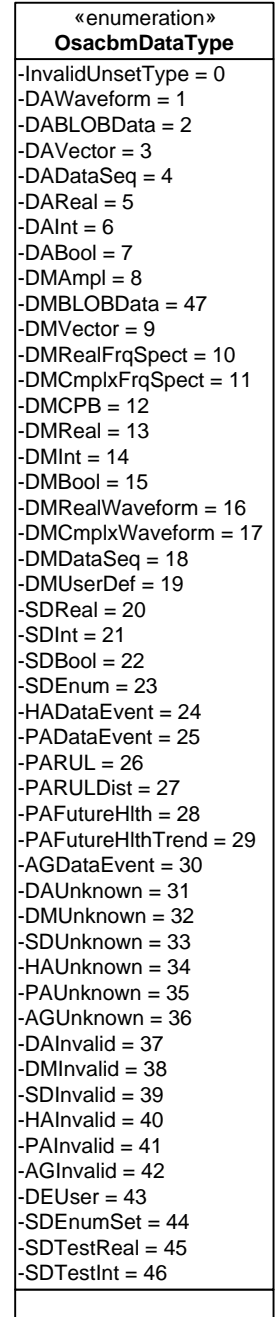
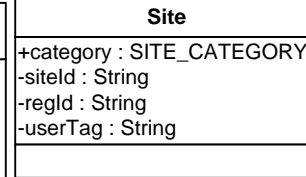
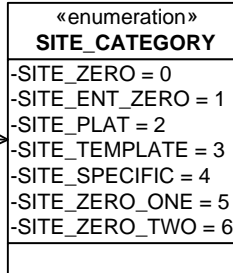
Site

Site is globally uniquely identified by one of two methods. Either the MIMOSA assigned 16 hex character siteld or the (regld, userTag) string combination where regld is assigned by MIMOSA for a specific registered user and the userTag is uniquely assigned by the registered user for each of the registered user's mobile platforms.

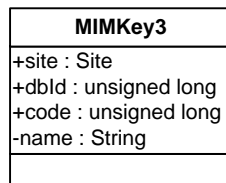
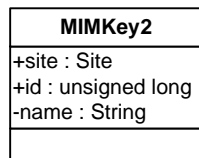
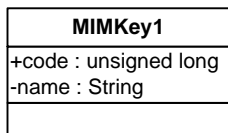
More specifics on these strings is described in the MIMOSA CRIS documentation.

SITE_CATEGORY indicates specific site types.

SITE_ZERO is MIMOSA (0, db_id=0).
SITE_ENT_ZERO is for platform enterprise site zero entry.
SITE_PLAT is for site platform.
SITE_TEMPLATE is for platform template.
SITE_SPECIFIC is for all other sites and needs to be added into the system directly or indirectly.
SITE_ZERO_ONE is MIMOSA (0,db_id=1).
SITE_ZERO_TWO is MIMOSA (0,db_id=2).
These are standard MIMOSA entry sets.



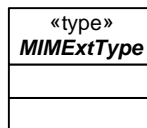
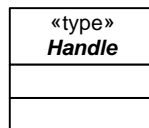
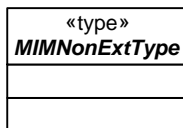
MIMKeys: MIMOSA Table Keys



MIMKey Type Defs

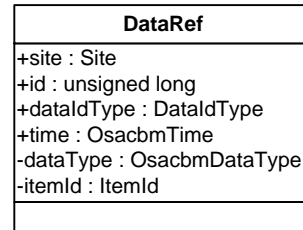
```

typedef MIMKey1 MIMNonExtType
typedef MIMKey2 Handle
typedef MIMKey3 MIMExtType
  
```



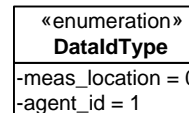
MIMNonExtType is a MIMOSA non-extensible type. It is therefore a single integer.
Handle is used to indicate a specific MIMOSA measurement location (DA, DM,SD) or agent id (HA,PA,AG).
MIMExtType is a MIMOSA extensible type. It has three keys: site, dbld, and code. (Handle, code) may be put into a MIMExtType number to form its value. In this case, it would typically refer to a MIMOSA database id.

DataReference



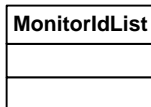
DataRef is a reference to one data item. It is essentially a descriptor to one DataEvent value. Explanation uses this as a type of data pointer.

DataIdType

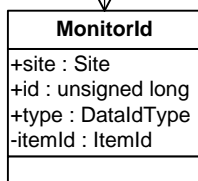


DataIdType describes what a DataEvent id is meant to be a reference to. OSA-CBM DataEvents from the lower three layers DA, DM, and SD are MIMOSA measurement locations. OSA-CBM DataEvents from the higher three layers, HA, PA, and AG, are MIMOSA agents. The DataEvent id's from these different data types therefore correspond to these two types of sources: agents and measurement locations.

MonitorIdList



0..1 -monitorId



MonitorIdList is used by interfaces to indicate the desired subset of served information by indicating the monitored measurement location, agent, or agent / item that is desired.

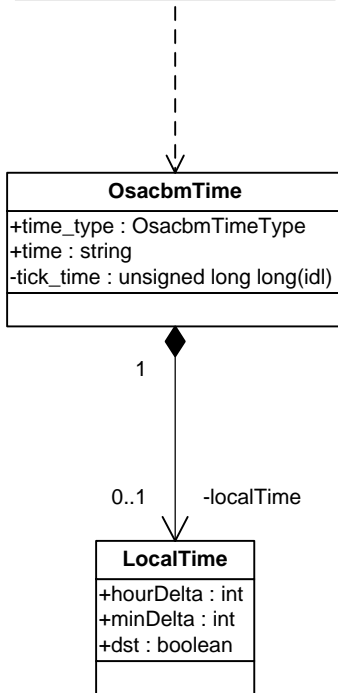
MonitorId is a reference to a monitored measurement location, agent, or agent / item.

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The Utility page details some classes that may be used or referenced elsewhere in this document.

Time

OSA-CBM uses the name `OsacbmTime` to eliminate name-clashing with other technologies.



Time has been expanded to have a few different internal content form types. This is to allow the simplest most direct method of handling time to be incorporated in an embedded program.

The MIMOSA type should be transmitted as a string conforming to ISO 8601. See description at side.

Tick time is presently defined for microseconds, with the data type long long. It is the number of ticks since start up of the program.

Posix is a Unix type time, which is also fetched in terms of the data type long long.

Methods to access specific time portions is highly desirable for any implementation. Any language implementation should have methods:

```

uint getYear()
uint getMonth()
...
ushort getHour()
...
ushort getMicrosec()
ushort getNanosec()
  
```

```

...
ushort getHour()
...
ushort getMicrosec()
ushort getNanosec()
  
```

methods should interpret Tick or Posix accordingly.

All rtn types are integer EXCEPT getTick which is an unsigned long long 64 bit int.

Date/time in ISO 8601 variable length character form:
 YYYY-MM-DDThh:mm:ss.ffffff
 example 2006-05-31T14:30:33.123

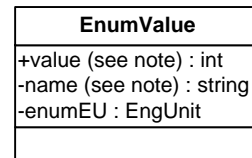
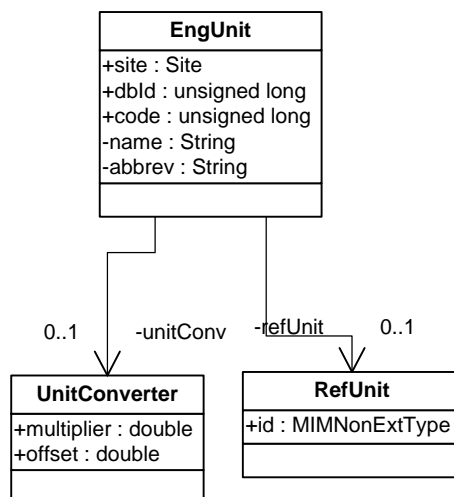
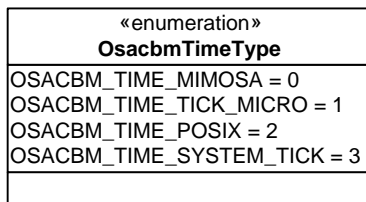
where:

YYYY = four-digit year
 MM = two-digit month (01=January, etc.)
 DD = two-digit day of month (01 through 31)
 hh = two digits of hour (00 through 23)
 (am/pm NOT allowed)
 T = literal "T" character
 mm = two digits of minute (00 through 59)
 ss = two digits of second (00 through 59)
 fffffff = represents a decimal fraction of a second to the billionth of a second

Year, month, and day must be specified. Additional timestamp content should be provided, if known. Zeros will be assumed for the omitted values. Negative DATETIME is not supported. All suffixes after the 29th character provided in the ISO 8601 specification, such as "Z" (representing Coordinated Universal Time (UTC)), are not necessary since the CRIS specification explicitly manages local offset hours and minutes as distinct columns associated with the UTC (referred to in the CRIS specification prefixed with "GMT") column.

Note that the actual difference between the new DATETIME(10:29) data type and the CRIS V2.1 fixed-length STRING(29) form is the separator between date and time information is now a literal T instead of a blank space, the separator for the billionths of seconds is now a dot (.) instead of a dash (-), and trailing items after the year-month-day fields may be omitted.

EngUnit and Enum Type

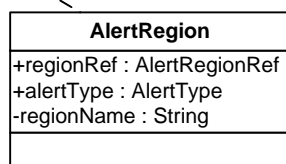


Enum value is uniquely identified by Eng Unit plus value. Name may be transmitted optionally.

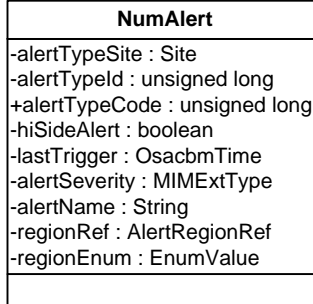
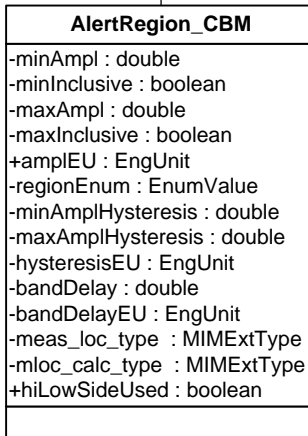
OutPort should have a corresponding EngUnit for transmitted values. Therefore, in a DataEvent transmission the DataEvent id can link to EngUnit from the OutPort and only a value may be needed in the actual DataEvent if shortness of expression is desired.

These classes must be implemented in a way that is open to extension by child class hierarchy.

Alerts and Regions



AlertRegion_CBM is an extensible type to allow for future growth in describing what should cause an alert.



NumAlert carries with it information about:

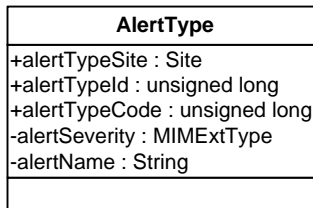
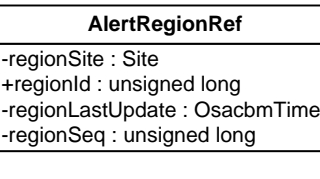
- (1) AlertType directly from AlertRegion.
- (2) Optional Time when AlertType was first entered.
- (3) Optional regionId for direct tie to the region.
- (4) Optional enum value associated with region.

Simplest usage is to use:

- 1) alertTypeCode set to predefined values.
- 2) OSA CBM convention is for unused alertTypeId to mean alertTypeId = 0 which should be based on platform Site.
- 3) OSA CBM convention is for unused alertTypeSite to mean use the Site found in the DataEventSet.

The DataEventSet Site is typically the platform Site. Thus unused alertTypeSite and alertTypeId corresponds to a MIMOSA database id of (platform_site, 0) .

- 4) Optional hiSideAlert and lastTrigger are useful.



regionId is a unique region identifier for the Site.

Usage Concept

A set of AlertRegions will be associated with a specific OutPort. The value associated with the AlertRegion set is the one contained in the DataEvent being output.

When the value contained in a DataEvent activates an AlertRegion the DataEvent will contain a NumAlert associated to the AlertRegion along with the time of occurrence stored in the lastTrigger. In a condition-based monitoring system, the following DataEvents from that OutPort will have new values and new times. However, the NumAlert will remain the same while in that region. This includes the lastTrigger time which may be used as an indicator of how long a particular region has been in effect.

When a Region is first entered it gives the specific DataEvent an "Alert Status". For CBM modules supporting "Alert Status" functionality, the output can be suppressed to output only when an alert trigger occurs. This mechanism requires one of the connected type interfaces.

(RegionId, OutPort handle) can be the identifier used by a higher module to control threshold levels via a user defined ControlVector. Future versions of the standard will begin to create a standard UML/XML form for this control.

Hysteresis BandDelay

Hysterisis and BandDelay are used to reduce threshold nuisance crossings. Region is activated when:

- 1) Threshold amplitude is crossed when no BandDelay and no Hysteresis.
- 2) Threshold amplitude is crossed for more than BandDelay time.
- 3) Threshold amplitude is crossed by more than Hysteresis value.
- 3) Threshold amplitude is crossed by more than Hysteresis value for BandDelay.

Hi-Low

hiLowSideUsed default is false. MIMOSA OSA-EAI does not presently have it and therefore it would be false for OSA-EAI apps.

The simplest method of use is to have a single set of alertRegions for an output and a direct set of alert types for those regions. The system should be set up so that AlertTypes and AlertRegions are all unique to the system and within the system. Then only a single int is needed to identify a code, the RegionId and the AlertTypeCode respectively. The Alert classes are based on the MIMOSA OSA EAI CRIS. Substitute the term Alert for Alarm. The OSA-CBM version has a few extra parameters like those for hysteresis and hiSideAlert indicator.

The main principles for optional arguments are:

For those terms that are primary keys in CRIS: if they are not used, then they should be elsewhere in the information schema, i.e. if Site is not specified use the site found in DataEventSet. For those terms that are not primary keys, like name, they may simply be expected to be found in a database. In short, assume that they are not needed for an operational monitoring system and would only make the system less efficient.

Data class for user definable types

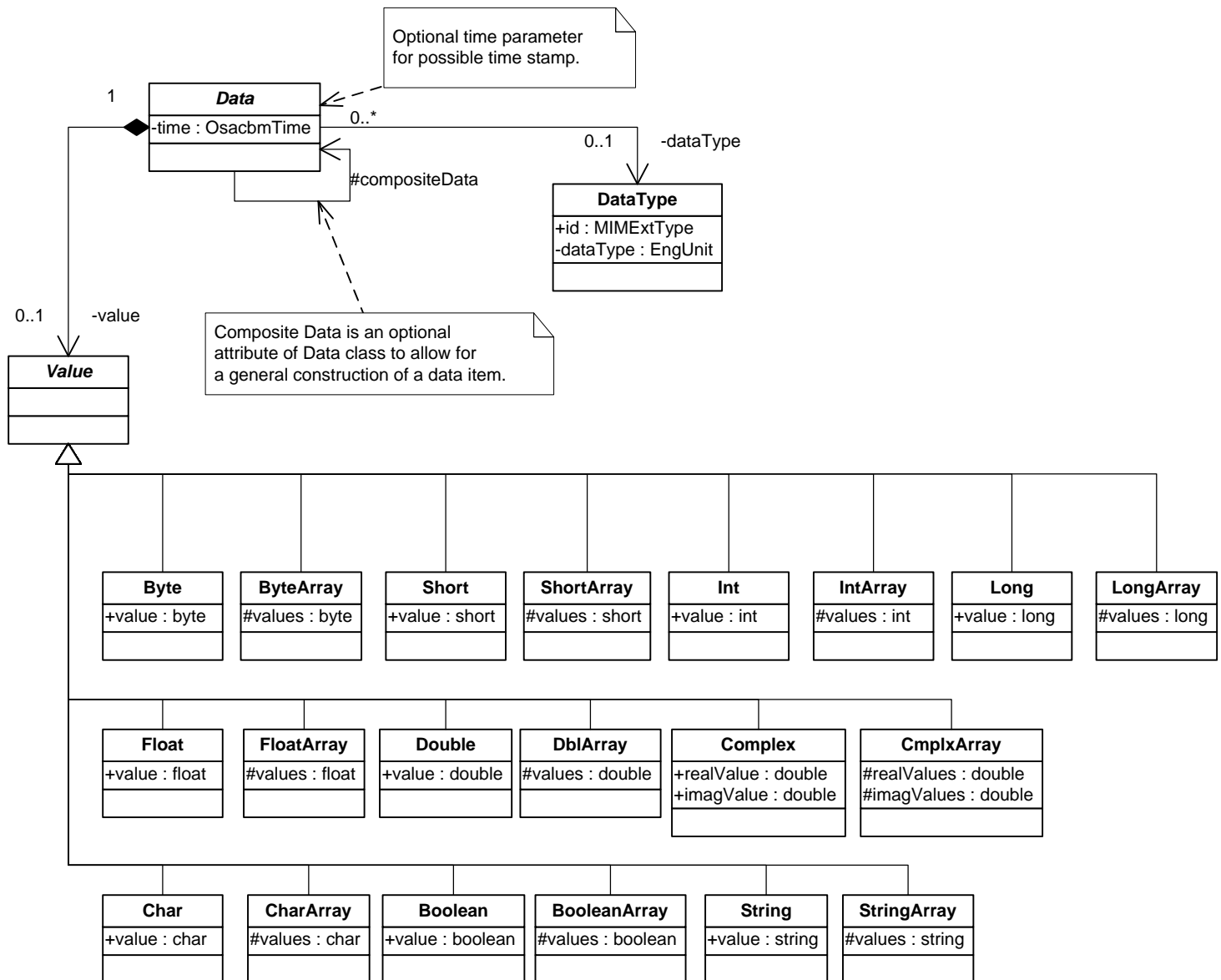
Data is mainly for user-definable types not in the OSA-CBM specification. This class set should be used mainly as a last resort. Please report any required use to the OSA-CBM technical subcommittee.

It is preferred that if there exists an information class that can contain your data in OSA-CBM then that should be used.

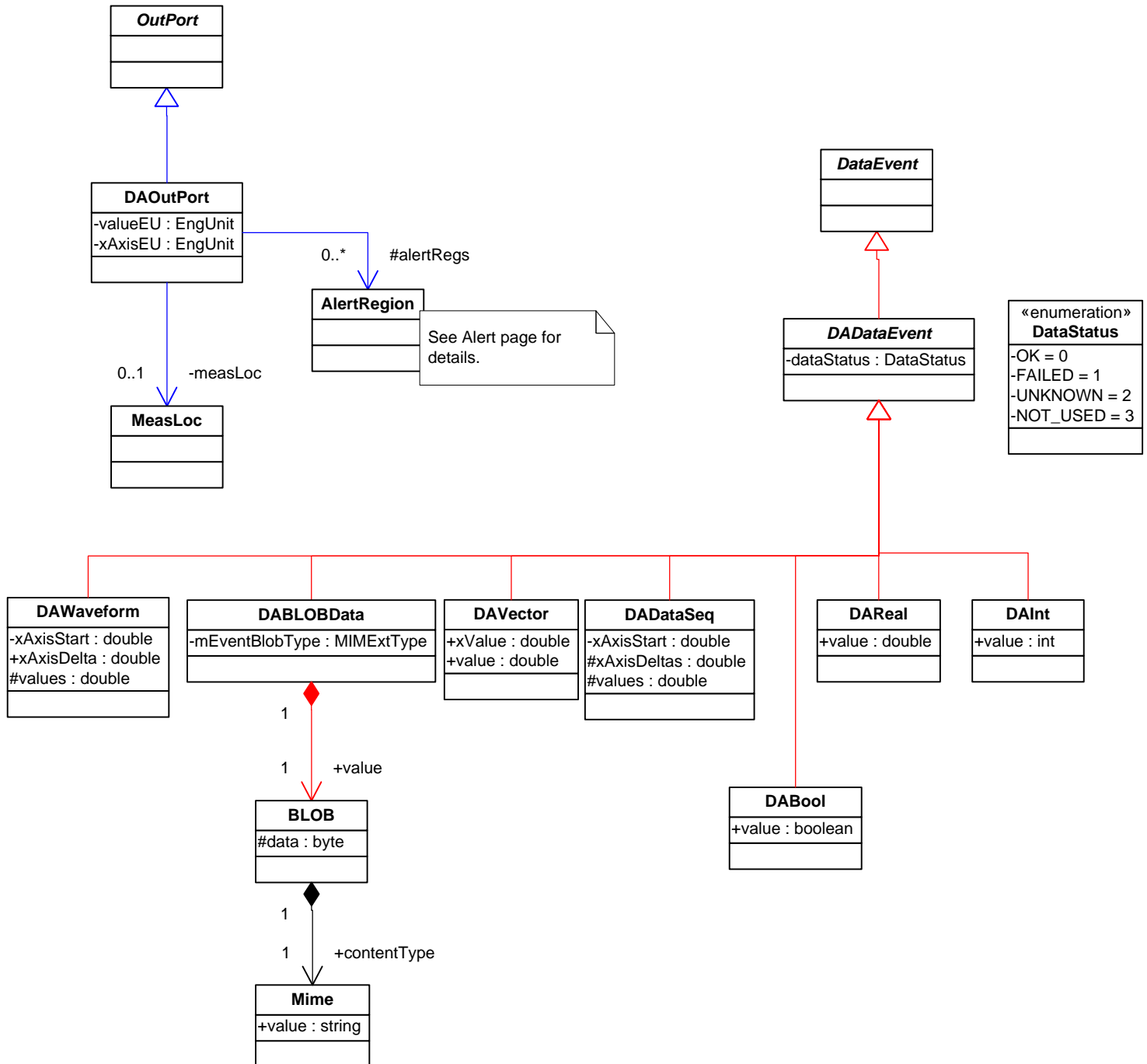
It is under consideration to have this removed if no valid use can be found.

The BLOB class is a more standardized and supported approach to sending data types that are not directly in the OSA-CBM specification.

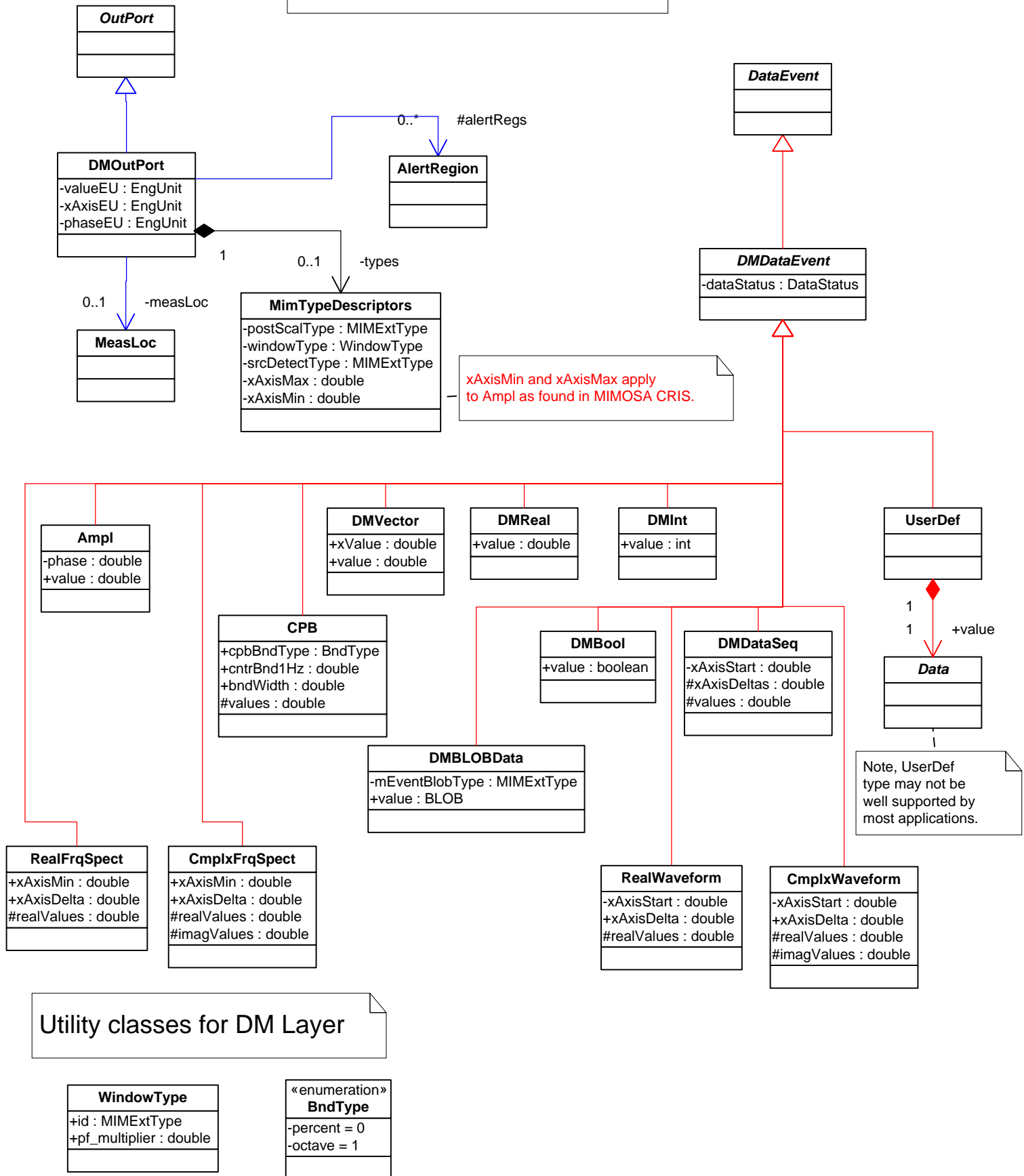
Additionally new types, such as multidimensional arrays, like wavelets can be added to the OSA-CBM specification fairly quickly.



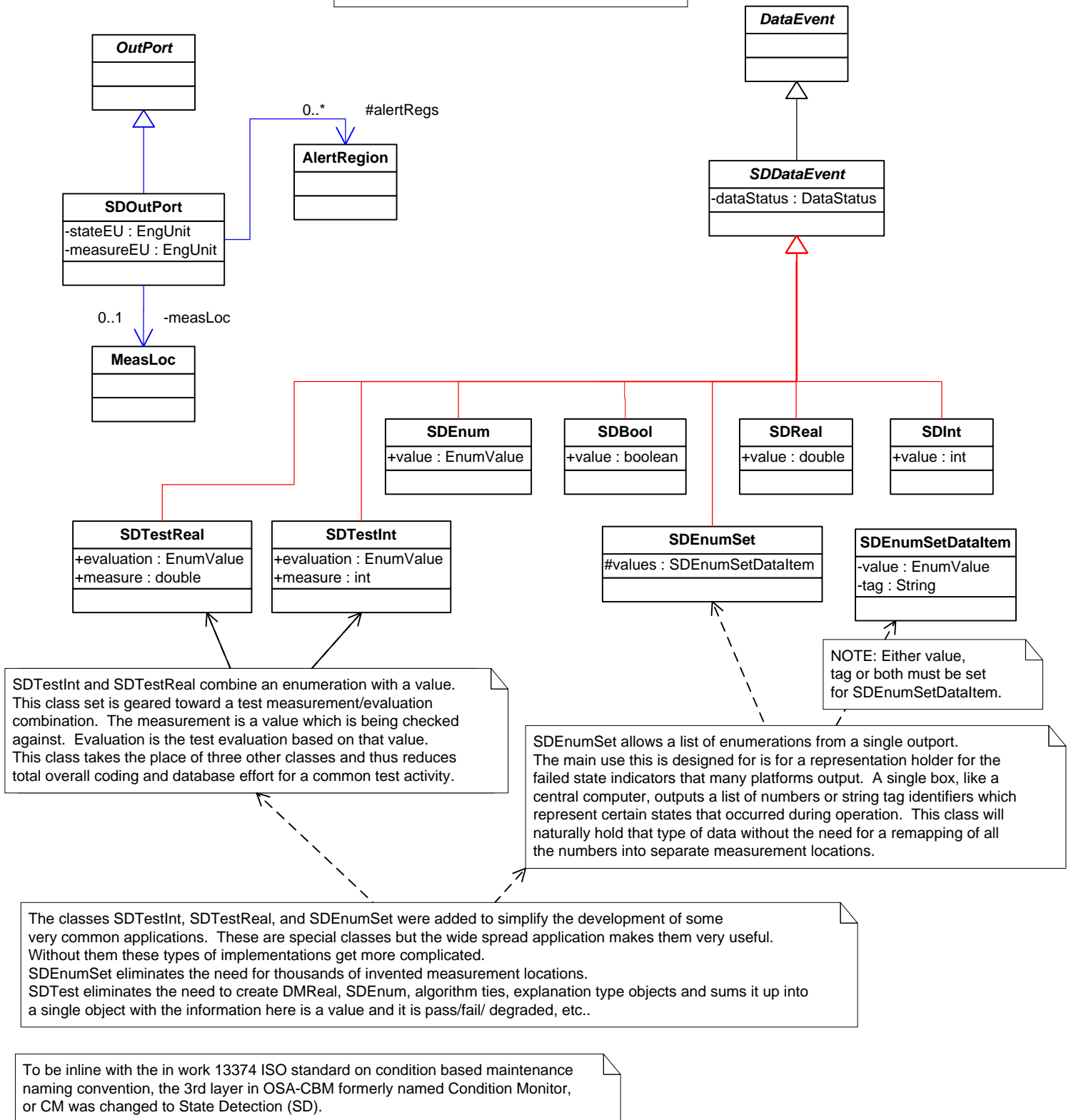
DA: Data Acquisition



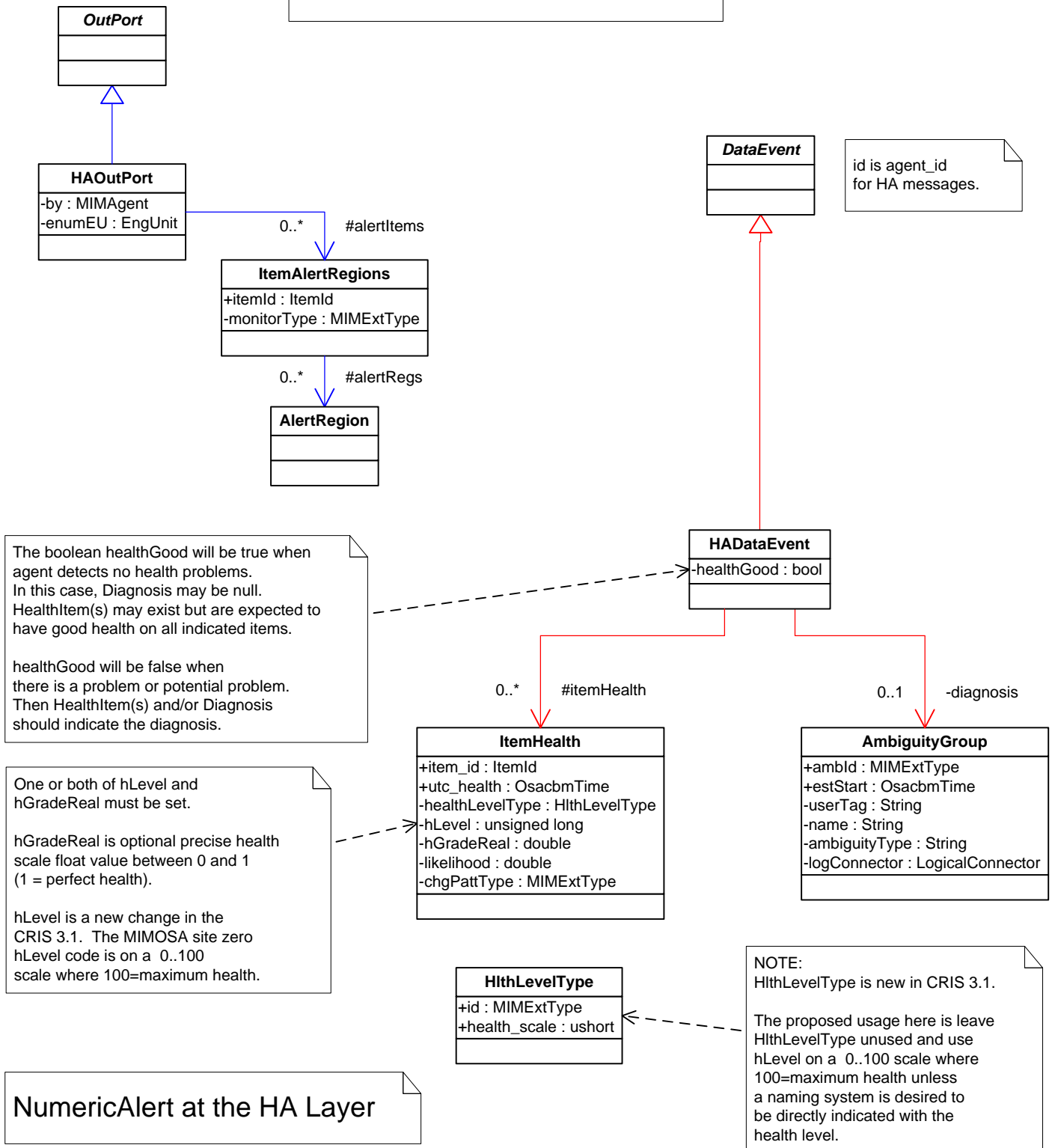
DM: Data Manipulation



SD: State Detection



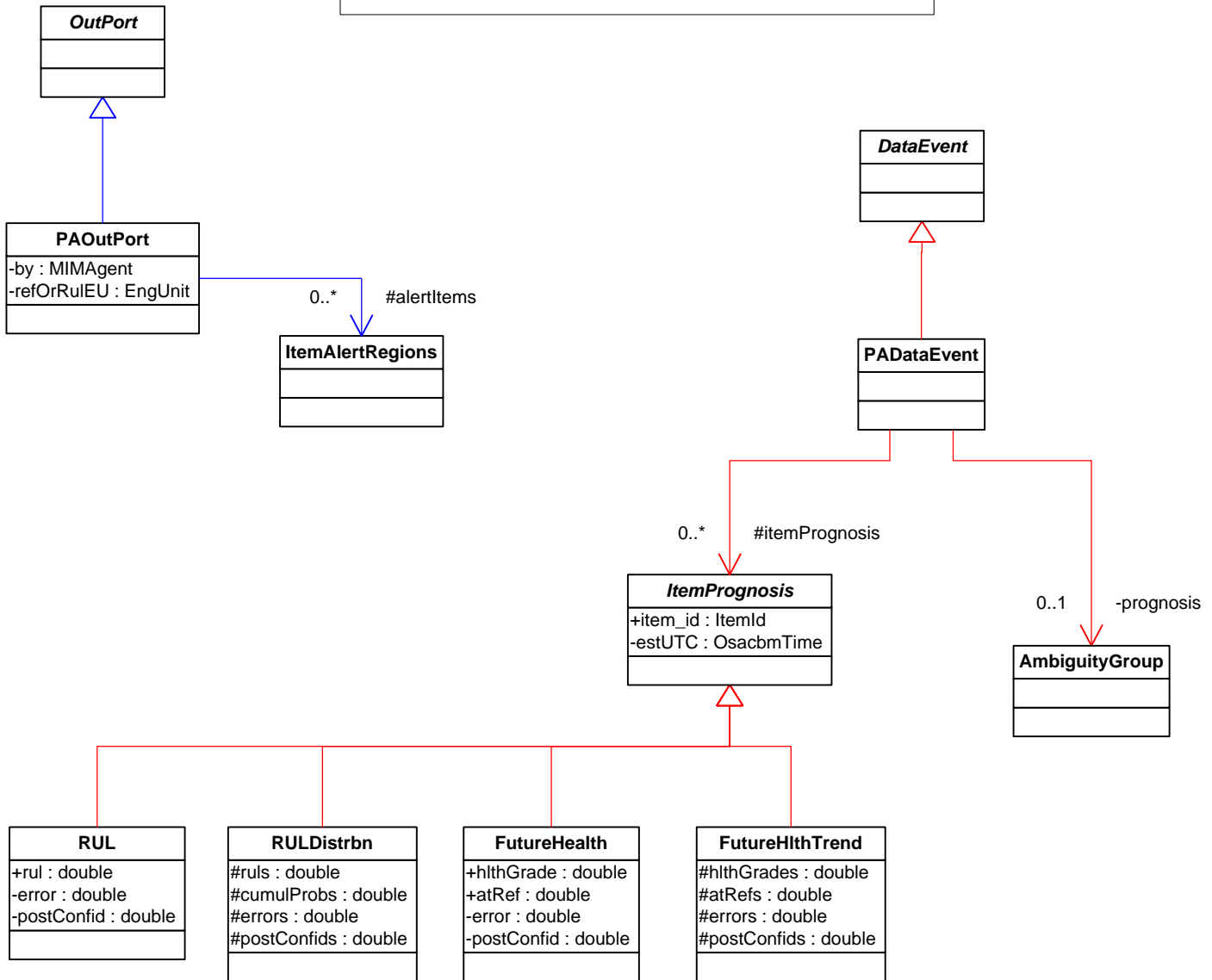
HA: Health Assessment



What would NumericAlert be used for in the HA Layer?

The main use would be to have an active monitor on the health grade of a component. This means the NumericAlert at the HA level requires the item monitored, i.e. ItemAlertRegions.

PA: Prognostics Assessment



RULDistrbn requires ruls and cumulProbs to be specified.
The arrays errors and postconfids are optional.

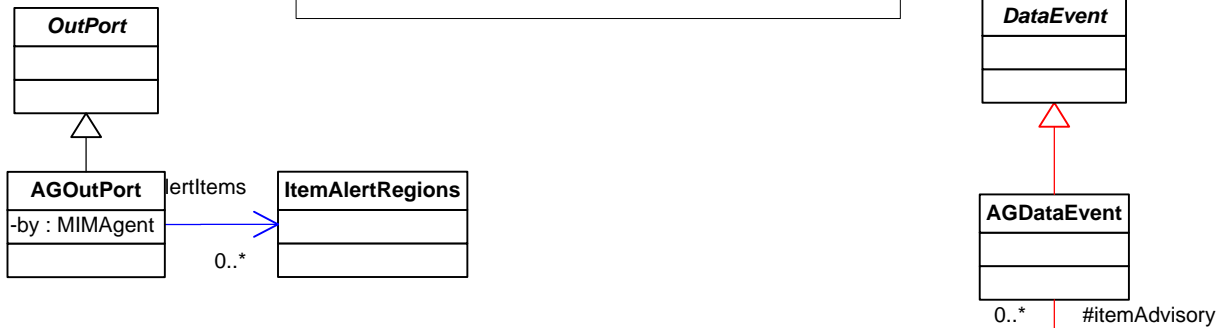
FutureHlthTrend requires hlthGrades and atRefs to be specified.
The arrays errors and postconfids are optional.

The length of all used arrays should be the same.

NumericAlert at the PA Layer

What would NumericAlert be used for in the PA Layer?
The main use would be to have an active monitor on the RUL or FutureHealth hlthGrade of a component. This means the NumericAlert at the PA level requires the item monitored.

AG: Advisory Generation



AG: Advisory Generation

The Advisory Generation is new in OSA-CBM. It allows for the direct request of maintenance for Assets and Segments. It associates to the following MIMOSA tables:

#134 - sg_req_for_work, #135 - as_req_for_work
 #184 - sg_recommendation, #185 - as_recommendation
 #130 - sg_rec_remark, #131 - as_rec_remark

These tables use the following utility tables:

#128 - work_manage_type, #108 - work_task_type,
 #106 - priority_type, #181 - solution_package

NumericAlert in the AG Layer

What would NumericAlert be used for in the AG Layer?

The main use would be to have an active monitor on the remaining time duration to maintenance for actively updated time to maintenance lists.

Note of possible extra needs:

Simply giving a start_before / start_after may be insufficient.

It may be good to have additional task_begin time:

- Before next flight
- Before next mission of type X
- Immediately upon arrival
- Next Periodic Maintenance event

Request for Work for Segment

NOTE: start_before_gmt - Request for action to begin before this time

NOTE: end_before_gmt - Request for action to end before this time

NOTE: start_after_gmt - Request for action to start after this time

NOTE: end_after_gmt - Request for action to end after this time

NOTE: from_sy_agent_site - System the request generated from

NOTE: repeat_interval - Time interval to automatically have work re-submitted for time-based actions

NOTE: int_eu_db_site, int_eu_db_id, int_eu_type_code - Time interval eng unit reference (hours, days, months, etc.)

NOTE: to_agent_site, to_agent_id - Agent to receive the request work

NOTE: sol_pack_db_site, sol_pack_db_id, sol_pack_id - Associated solution package

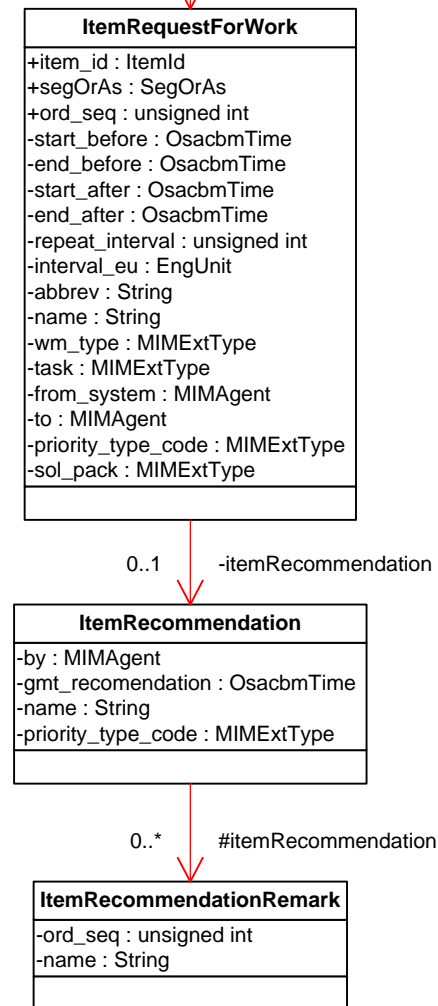
NOTE: rec_segment_site, rec_segment_id, rec_gmt_recomm, rec_by_agent_site, ec_by_agent_id

- Associated segment recommendation

NOTE: work_req_db_site, work_req_db_id, work_req_id - Associated Work Request in local or remote database

NOTE: abbrev - User-generated short work description

NOTE: name - User-generated full work description



Start of Note Pages

This pages ends the UML specification
and starts the notes pages for OSA-CBM.

Notes

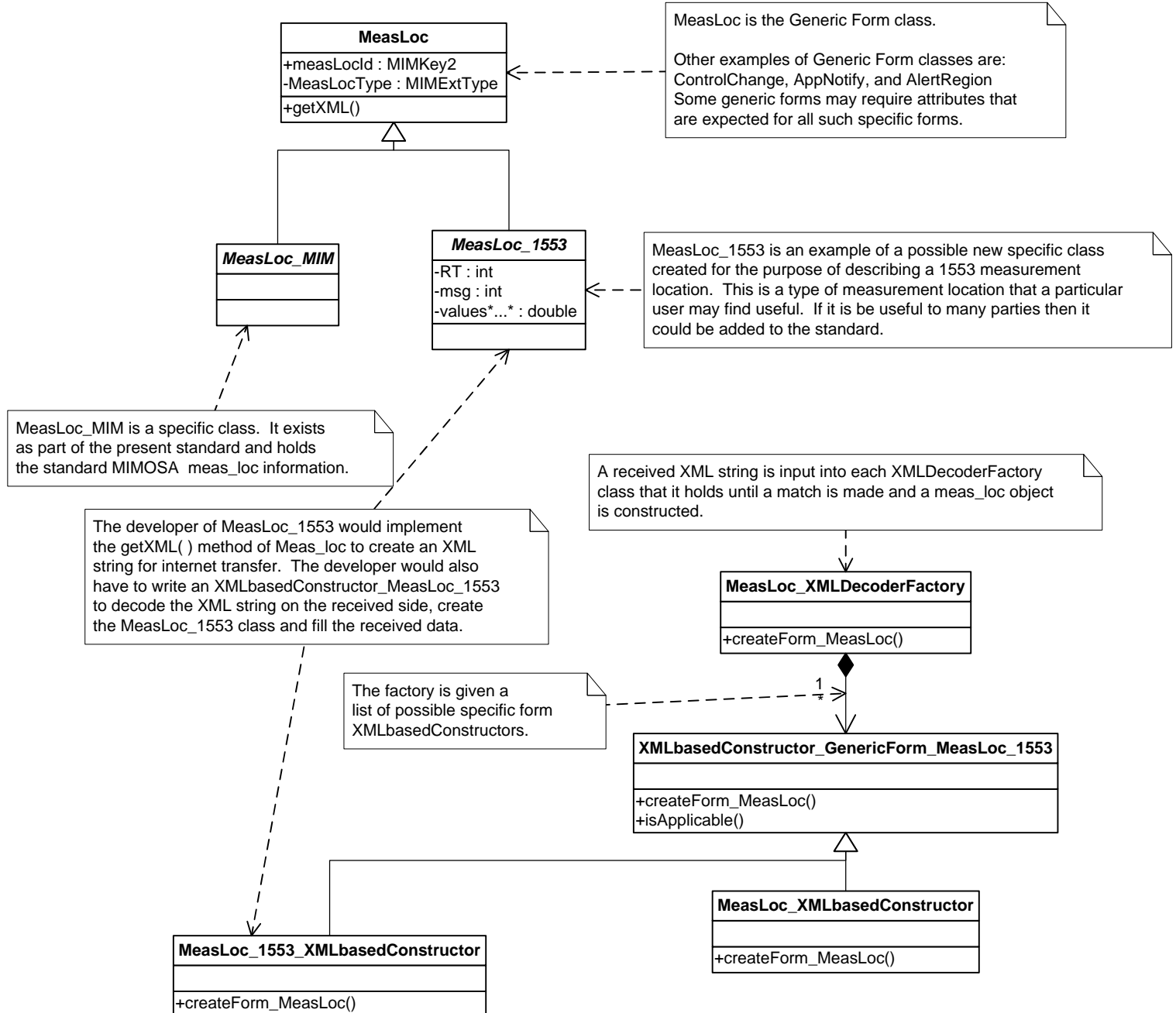
XML Extensibility Concept

Extensible type classes are for application specific purposes. IVHM applications may require these specific categories of information for setup and control. These classes allow for a standard way to input and output application specific XML. The getXML is a suggested method for a parent wrapper class.

The main concept is to have a class that is closed to modification but extensible to users
The XML string is used as the conveyor of data.

Implementations should have a getXML(...) method to retrieve a transmittable XML form.

Specific Implementations can use the specific form class structure.



Mapping Methodologies

Mapping Methodologies

The goal is to have OSA-CBM map totally seamlessly into OSA-EAI. The grand picture is the following.

1. Simple 1-to-1 information component mapping.
2. OSA-CBM extensions to CRIS that have extra information that OSA-EAI does not need.
3. A mapping document where difficult mappings or mappings that have many potential solutions are specified to be done in only one way.

The following provides a quick overview.

Perhaps 90% or more of OSA-CBM will mapping directly into OSA-EAI with ease.

There will be some changes and additions in OSA-EAI to facilitate the mapping also.

However there are certain differences and some OSA-CBM needs which are to be handled by OSA-CBM extensions in the MIMOSA specification.

The main requirement for the extensions deals with the ability to get data out of database storage in the original OSA-CBM format with all class structure intact and easily retrievable by a generic mechanism rather than having to hard code an expected form for a particular known configuration.

Main areas for the extensions includes

- 1) The OSA-CBM class-type definition specifics.

The ability to know which OSA-CBM class was used to transmit the data.

- 2) OSACBM time stamp based message identification scheme.

In OSA-CBM all messages such as measurement_events and health_assessments which includes proposed_events are identified by agent or meas_location, time stamp, and item id in the HA and PA layers. OSACBM small signature vehicles are not expected to generate new integer primary key signatures. The ability to do that would require non-volatile memory storage of some form to remember last number used.

Instead, OSA-CBM offers a slightly different primary key basis (agent, time, item).

All the same important information components as those found in OSA-EAI are there.

When such a message reaches a the OSA-EAI database location the OSA-EAI proposed event primary key signature may be generated.

- 3) Ambiguity Groups

OSA-EAI (V3.2?) will be enhanced to accommodate ambiguity groups.

- 4) Explanation

Explanation is the ability to state connection between data used as input and resultant data.

The OSA-CBM explanation uses references within the OSA-CBM context. OSA-CBM extensions Explanation table will be used by those desiring this information to be retrievable.

OSA-EAI has many data tie tables for those desiring this information tie in the OSA-EAI context.